# TURNPIKE PHENOMENON FOR SYMMETRIC VARIATIONAL PROBLEMS 

ALEXANDER J. ZASLAVSKI<br>Department of Mathematics, The Technion - Israel Institute of Technology, Haifa, Israel<br>Dedicated to the memory of Professor Ram Verma


#### Abstract

In our recent research we studied the turnpike phenomenon for a class of symmetric variational problems. For this class of problems integrands possess two points of minimum and a certain well-posedness property holds. In this paper, we show that some versions of the turnpike property hold if a set of minimizers of an integrand is finite.


Keywords. Integrand; Symmetry; Turnpike; Variational problem.

## 1. Introduction

The study of the existence and the structure of solutions of variational problems, optimal control problems and dynamic games defined on infinite intervals and on sufficiently large intervals has been a rapidly growing area of research $[3,4,10,11,16,19,21,22,24,37,39$, $40,47,66,69,71,74,75,76,79]$ which has various applications in engineering $[1,16,66]$, in models of economic growth $[2,15,16,20,25,35,36,38,42,46,52,60,61,64,66,76]$, in infinite discrete models of solid-state physics related to dislocations in one-dimensional crystals [5, 65], in model predictive control [18,27] and in the theory of thermodynamical equilibrium for materials [17, 43, 49, 50, 51]. Discrete-time problems optimal control problems were considered in $[3,6,7,14,23,33]$, finite-dimensional continuous-time problems were analyzed in [10, 12, 13, 42, 45, 48, 56, 70, 77, 78], infinite-dimensional optimal control was studied in [16, 28, 29, 30, 54, 55,57, 59, 62, 63, 80] while solutions of dynamic games were discussed in [ $9,26,31,34,41,58,68,72,73]$.

In this paper we study the turnpike phenomenon for symmetric variational problems in infinite dimensional spaces. To have the turnpike property means, roughly speaking, that the approximate solutions of the problems are determined mainly by the objective function and are essentially independent of the choice of interval and endpoint conditions, except in regions close to the endpoints.

[^0]The turnpike property was discovered by P. Samuelson in 1948 when he showed that an efficient expanding economy would spend most of the time in the vicinity of a balanced equilibrium path (also called a von Neumann path). It is well known in the economic literature, where it was studied for various models of economic growth. Usually for these models a turnpike is a singleton.

Now it is well-known that the turnpike property is a general phenomenon which holds for large classes of variational and optimal control problems. In our research, using the Baire category (generic) approach, it was shown that the turnpike property holds for a generic (typical) variational problem [66] and for a generic optimal control problem [70].

In this paper we are interested in individual (non-generic) turnpike results for symmetric variational problems. These problems have applications in crystallography [32, 53, 67]. In our recent research [81] we studied the turnpike phenomenon for a class of symmetric variational problems with integrands possessing two points of minimum and a certain well-posedness property. In this paper, we show that some versions of the turnpike property hold if a set of minimizers of an integrand is finite.

## 2. BANACH SPACE VALUED FUNCTIONS

In this section we present preliminaries which we need in order to study turnpike properties of infinite dimensional variational problems.

Let $(X,\|\cdot\|)$ be a Banach space and $a<b$ be real numbers. For any set $E \subset R^{1}$ define

$$
\chi_{E}(t)=1 \text { for all } t \in E \text { and } \chi_{E}(t)=0 \text { for all } t \in R^{1} \backslash E .
$$

If a set $E \subset R^{1}$ is Lebesgue measurable, then its Lebesgue measure is denoted by $|E|$ or by $\operatorname{mes}(E)$.

A function $f:[a, b] \rightarrow X$ is called a simple function if there exists a finite collection of Lebesgue measurable sets $E_{i} \subset[a, b], i \in I$, mutually disjoint, and $x_{i} \in X, i \in I$ such that

$$
f(t)=\sum_{i \in I} \chi_{E_{i}}(t) x_{i}, t \in[a, b] .
$$

A function $f:[a, b] \rightarrow X$ is strongly measurable if there exists a sequence of simple functions $\phi_{k}:[a, b] \rightarrow X, k=1,2, \ldots$ such that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|\phi_{k}(t)-f(t)\right\|=0, t \in[a, b] \text { almost everywhere (a. e.). } \tag{2.1}
\end{equation*}
$$

For every simple function $f(\cdot)=\sum_{i \in I} \chi_{E_{i}}(\cdot) x_{i}$, where the set $I$ is finite, define its Bochner integral by

$$
\int_{a}^{b} f(t) d t=\sum_{i \in I}\left|E_{i}\right| x_{i}
$$

Let $f:[a, b] \rightarrow X$ be a strongly measurable function. We say that $f$ is Bochner integrable if there exists a sequence of simple functions $\phi_{k}:[a, b] \rightarrow X, k=1,2, \ldots$ such that (2.1) holds and the sequence $\left\{\int_{a}^{b} \phi_{k}(t) d t\right\}_{k=1}^{\infty}$ strongly converges in $X$. In this case we define the Bochner integral of the function $f$ by

$$
\int_{a}^{b} f(t) d t=\lim _{k \rightarrow \infty} \int_{a}^{b} \phi_{k}(t) d t
$$

It is known that the integral defined above is independent of the choice of the sequence $\left\{\phi_{k}\right\}_{k=1}^{\infty}$ [44]. Similar to the Lebesgue integral, for any measurable set $E \subset[a, b]$, the Bochner integral of $f$ over $E$ is defined by

$$
\int_{E} f(t) d t=\int_{a}^{b} \chi_{E}(t) f(t) d t
$$

The following result is true (see Proposition 3.4, Chapter 2 of [44]).
Proposition 2.1. Let $f:[a, b] \rightarrow X$ be a strongly measurable function. Then $f$ is Bochner integrable if and only if the function $\|f(\cdot)\|$ is Lebesgue integrable. Moreover, in this case

$$
\left\|\int_{a}^{b} f(t) d t\right\| \leq \int_{a}^{b}\|f(t)\| d t
$$

The Bochner integral possesses almost the same properties as the Lebesgue integral. If $f$ : $[a, b] \rightarrow X$ is strongly measurable and $\|f(\cdot)\| \in L^{p}(a, b)$, for some $p \in[1, \infty)$, then we say that $f(\cdot)$ is $L^{p}$ Bochner integrable. For every $p \geq 1$, the set of all $L^{p}$ Bochner integrable functions is denoted by $L^{p}(a, b ; X)$ and for every $f \in L^{p}(a, b ; X)$,

$$
\|f\|_{L^{p}(a, b ; X)}=\left(\int_{a}^{b}\|f(t)\|^{p} d t\right)^{1 / p}
$$

Clearly, the set of all Bochner integrable functions on $[a, b]$ is $L^{1}(a, b ; X)$.
Let $a<b$ be real numbers. A function $x:[a, b] \rightarrow X$ is absolutely continuous (a. c.) on $[a, b]$ if for each $\varepsilon>0$ there exists $\delta>0$ such that for each pair of sequences $\left\{t_{n}\right\}_{n=1}^{q},\left\{s_{n}\right\}_{n=1}^{q} \subset[a, b]$ satisfying

$$
\begin{gathered}
t_{n}<s_{n}, n=1, \ldots, q, \sum_{n=1}^{q}\left(s_{n}-t_{n}\right) \leq \boldsymbol{\delta} \\
\left(t_{n}, s_{n}\right) \cap\left(t_{m}, s_{m}\right)=\emptyset \text { for all } m, n \in\{1, \ldots, q\} \text { such that } m \neq n
\end{gathered}
$$

we have

$$
\sum_{n=1}^{q}\left\|x\left(t_{n}\right)-x\left(s_{n}\right)\right\| \leq \varepsilon
$$

The following result is true (see Theorem 1.124 of [8]).
Proposition 2.2. Let $X$ be a reflexive Banach space. Then every a. c. function $x:[a, b] \rightarrow X$ is a. e. differentiable on $[a, b]$ and

$$
x(t)=x(a)+\int_{a}^{t}(d x / d t)(s) d s, t \in[a, b]
$$

where $d x / d t \in L^{1}(a, b ; X)$ is the strong derivative of $x$.
Let $-\infty<\tau_{1}<\tau_{2}<\infty$. Denote by $W^{1,1}\left(\tau_{1}, \tau_{2} ; X\right)$ (or $W^{1,1}\left(\tau_{1}, \tau_{2}\right)$ if the space $X$ is understood) the set of all functions $x:\left[\tau_{1}, \tau_{2}\right] \rightarrow X$ for which there exists a Bochner integrable function $u:\left[\tau_{1}, \tau_{2}\right] \rightarrow X$ such that for all $t \in\left(\tau_{1}, \tau_{2}\right]$,

$$
x(t)=x\left(\tau_{1}\right)+\int_{\tau_{1}}^{t} u(s) d s
$$

## 3. SyMMETRIC VARIATIONAL PROBLEMS

In this section we begin to study the turnpike properties for symmetric variational problems in Banach spaces. To have the turnpike property means, roughly speaking, that the approximate solutions of the problems are determined mainly by the integrand and are essentially independent of the choice of interval and endpoint conditions, except in regions close to the endpoints.

Assume that $(X,\|\cdot\|)$ is a Banach space. For each $x \in X$ and each $r>0$ set

$$
B(x, r)=\{y \in X:\|y-x\| \leq r\} .
$$

Suppose that the infimum over an empty set is $\infty$, the sum over an empty set is zero and denote by $\operatorname{Card}(C)$ the cardinality of a set C .

Assume that $f: X \times X \rightarrow R^{1}$ is a bounded from below borelian function such that

$$
\begin{equation*}
f(x, y)=f(x,-y) \text { for all } x, y \in X \tag{3.1}
\end{equation*}
$$

$m$ is a natural number and there exists $\left(\bar{x}_{i}, \bar{y}_{i}\right) \in X \times X, i=1, \ldots, m$ such that

$$
\begin{gather*}
\bar{x}_{i} \neq \bar{x}_{j} \text { for each } i, j \in\{1, \ldots, m\} \text { satisfying } i \neq j, \\
\inf (f):=\inf \{f(\xi, \eta): \xi, \eta \in X\}  \tag{3.2}\\
\{(x, y) \in X \times X:  \tag{3.3}\\
f(x, y)=\inf (f)\}=\left\{\left(\bar{x}_{i}, \bar{y}_{i}\right),\left(\bar{x}_{i},-\bar{y}_{i}\right): i=1, \ldots, m\right\} .
\end{gather*}
$$

(Note that it is possible that $\bar{y}_{i}=0$ for some $i \in\{1, \ldots, m\}$.)
Assume that the following assumptions hold:
(A1) for each $\varepsilon>0$ there exists $\delta>0$ such that for each $(x, y) \in X \times X$ satisfying

$$
f(x, y) \leq \inf (f)+\delta
$$

there exists $i \in\{1, \ldots, m\}$ such that the inequalities

$$
\left\|x-\bar{x}_{i}\right\| \leq \varepsilon
$$

and

$$
\min \left\{\left\|y-\bar{y}_{i}\right\|,\left\|y+\bar{y}_{i}\right\|\right\} \leq \varepsilon
$$

hold;
(A2) for each $\varepsilon>0$ there exists $\delta>0$ such that for each $i \in\{1, \ldots, m\}$ and each $(x, y) \in X \times X$ satisfying

$$
\left\|x-\bar{x}_{i}\right\| \leq \delta,\left\|y-\bar{y}_{i}\right\| \leq \delta
$$

the inequality

$$
f(x, y) \leq f\left(\bar{x}_{i}, \bar{y}_{i}\right)+\varepsilon
$$

is true.
Assumption (A2) means that the function $f$ is continuous at the points $\left(\bar{x}_{i}, \bar{y}_{i}\right), i=1, \ldots, m$ while assumption (A1) means that the minimization problem

$$
f(x, y) \rightarrow \min , x, y \in X
$$

is well posed in a generalized sense.
Let $a>0$ and $\psi:[0, \infty) \rightarrow[0, \infty)$ be an increasing function satisfying

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \psi(t)=\infty \tag{3.4}
\end{equation*}
$$

Assume that the following assumption holds:
(A3) the function $f$ is bounded on all bounded sets and for each $(x, u) \in X \times X$,

$$
f(x, u) \geq \psi(\|u\|)\|u\|-a
$$

For each pair of nonnegative numbers $T_{1}<T_{2}$ and each $y, z \in X$ we consider the problems

$$
\begin{gather*}
\int_{T_{1}}^{T_{2}} f\left(x(t), x^{\prime}(t)\right) d t \rightarrow \min , \\
x \in W^{1,1}\left(T_{1}, T_{2}\right), \\
\int_{T_{1}}^{T_{2}} f\left(x(t), x^{\prime}(t)\right) d t \rightarrow \min ,  \tag{1}\\
x \in W^{1,1}\left(T_{1}, T_{2}\right), x\left(T_{1}\right)=y, \\
\int_{T_{1}, T_{2}}^{T_{2}} f\left(x(t), x^{\prime}(t)\right) d t \rightarrow \min , \\
x \in W^{1,1}\left(T_{1}, T_{2}\right), x\left(T_{1}\right)=y, x\left(T_{2}\right)=z
\end{gather*}
$$

and define

$$
\begin{gathered}
U\left(T_{1}, T_{2}\right)=\inf \left\{\int_{T_{1}}^{T_{2}} f\left(x(t), x^{\prime}(t)\right) d t: x \in W^{1,1}\left(T_{1}, T_{2}\right)\right\} \\
U\left(T_{1}, T_{2}, y\right)=\inf \left\{\int_{T_{1}}^{T_{2}} f\left(x(t), x^{\prime}(t)\right) d t: x \in W^{1,1}\left(T_{1}, T_{2}\right), x\left(T_{1}\right)=y\right\} \\
U\left(T_{1}, T_{2}, y, z\right)=\inf \left\{\int_{T_{1}}^{T_{2}} f\left(x(t), x^{\prime}(t)\right) d t\right. \\
\left.x \in W^{1,1}\left(T_{1}, T_{2}\right), x\left(T_{1}\right)=y, x\left(T_{2}\right)=z\right\}
\end{gathered}
$$

Let $i \in\{1, \ldots, m\}$. There are two cases: $\bar{y}_{i}=0 ; \bar{y}_{i} \neq 0$. If $\bar{y}_{i}=0$, then for each $T_{2}>T_{1} \geq 0$, the function $x(t)=\bar{x}_{i}, t \in\left[T_{1}, T_{2}\right]$ is a solution of the problems $\left(P_{T_{1}, T_{2}}\right),\left(P_{T_{1}, T_{2}, \bar{x}_{i}}\right),\left(P_{T_{1}, T_{2}, \bar{x}_{i}, \bar{x}_{i}}\right)$.

For each pair of numbers $T_{1}<T_{2}$ and each $x \in W^{1,1}\left(T_{1}, T_{2}\right)$ set

$$
I\left(T_{1}, T_{2}, x\right)=\int_{T_{1}}^{T_{2}} f\left(x(t), x^{\prime}(t)\right) d t
$$

Analogously to Theorem 5.1 of [81] we can prove the following result.
Theorem 3.1. Let $T>0$ and $i \in\{1, \ldots, m\}$. Then

$$
U(0, T)=U\left(0, T, \bar{x}_{i}\right)=U\left(0, T, \bar{x}_{i}, \bar{x}_{I}\right)=T f\left(\bar{x}_{i}, \bar{y}_{i}\right)
$$

Moreover, for each $\varepsilon>0$ there exists $x \in W^{1,1}(0, T)$ such that

$$
\begin{gathered}
x(0)=x(T)=\bar{x}_{i}, \\
I(0, T, x) \leq T f\left(\bar{x}_{i}, \bar{y}_{i}\right)+\varepsilon, \\
\left\|x(t)-\bar{x}_{i}\right\| \leq \varepsilon, t \in[0, T], \\
x^{\prime}(t) \in\left\{\bar{y}_{i},-\bar{y}_{I}\right\}, t \in[0, T] \text { a. e.. }
\end{gathered}
$$

Analogously to Theorem 5.2 of [81] we can prove the following result.
Theorem 3.2. Let $L_{0}, M_{0}>0$. Then there exist $M_{1}>0$ such that for each $T>L_{0}$ and each $y, z \in X$ satisfying $\|y\|,\|z\| \leq M_{0}$ the inequality

$$
U(0, T, y, z) \leq T f\left(\bar{x}_{1}, \bar{y}_{1}\right)+M_{1}
$$

holds.

## 4. The first weak turnpike result

In this section we prove our first turnpike result. It shows that for approximate solutions $x$ of our variational problems on intervals $[0, T]$, where $T$ is sufficiently large and given values $x(0), x(T)$ at the end points belong to a given bounded set $C$, the Lebesgue measure of all points $t \in[0, T]$ such that $\left(x(t), x^{\prime}(t)\right)$ does not belong to an $\varepsilon$-neighborhood of the set $\left\{\left(\bar{x}_{i}, \bar{y}_{i}\right),\left(\bar{x}_{i},-\bar{y}_{i}\right): i=1, \ldots, m\right\}$ does not exceed a constant $L$ which depends only on $\varepsilon$ and the set $C$ and does not depend on $T, x(0), x(T)$. In the literature this property is known as the weak turnpike property.

Theorem 4.1. Let $\varepsilon \in(0,1)$ and $L_{0}, M_{0}, M_{1}>0$. Then there exists $L_{1}>L_{0}$ such that for each $T>L_{1}$ and each $x \in W^{1,1}(0, T)$ such that

$$
\begin{equation*}
x(0) \in B\left(0, M_{0}\right) \tag{4.1}
\end{equation*}
$$

and at least one of the following conditions holds:
(a)

$$
x(T) \in B\left(0, M_{0}\right), I^{f}(0, T, x) \leq U(0, T, x(0), x(T))+M_{1}
$$

(b)

$$
I^{f}(0, T, x) \leq U(0, T, x(0))+M_{1}
$$

the inequality

$$
\begin{gathered}
\operatorname{mes}\left(\left\{t \in[0, T]: \max \left\{\left\|x(t)-\bar{x}_{i}\right\|,\right.\right.\right. \\
\left.\left.\left.\min \left\{\left\|x^{\prime}(t)-\bar{y}_{i}\right\|,\left\|x^{\prime}(t)+\bar{y}_{i}\right\|\right\}\right\}>\varepsilon \text { for each } i \in\{1, \ldots, m\}\right\}\right) \leq L_{1}
\end{gathered}
$$

Proof. Theorem 3.2 implies that there exists $M_{2}>0$ such that for each $T>L_{0}$ and each $y, z \in$ $B\left(0, M_{0}\right)$,

$$
\begin{equation*}
U(0, T, y, z) \leq T f\left(\bar{x}_{1}, \bar{y}_{1}\right)+M_{2} \tag{4.2}
\end{equation*}
$$

Assumption (A1) implies that there exists $\delta \in(0, \boldsymbol{\varepsilon})$ such that for each $(x, y) \in X \times X$ satisfying for each $i \in\{1, \ldots, m\}$,

$$
\begin{equation*}
\max \left\{\left\|x-\bar{x}_{i}\right\|+\min \left\{\left\|y-\bar{y}_{i}\right\|,\left\|y+\bar{y}_{i}\right\|\right\}\right\}>\varepsilon \tag{4.3}
\end{equation*}
$$

we have

$$
\begin{equation*}
f(x, y)>f\left(\bar{x}_{i}, \bar{y}_{i}\right)+\delta \tag{4.4}
\end{equation*}
$$

Set

$$
\begin{equation*}
L_{1}=\max \left\{L_{0}, \delta^{-1}\left(M_{1}+M_{2}\right)\right\}+1 \tag{4.5}
\end{equation*}
$$

Assume that $T>L_{1}, x \in W^{1,1}(0, T)$, (4.1) is true and at least one of conditions (a) and (b) holds. Conditions (a) and (b) and (4.1), (4.2), (4.5) imply that

$$
\begin{equation*}
I^{f}(0, T, x) \leq T f\left(\bar{x}_{1}, \bar{y}_{1}\right)+M_{1}+M_{2} \tag{4.6}
\end{equation*}
$$

Set

$$
\begin{equation*}
E=\left\{t \in[0, T]: f\left(x(t), x^{\prime}(t)\right)>f\left(\bar{x}_{1}, \bar{y}_{1}\right)+\delta\right\} . \tag{4.7}
\end{equation*}
$$

Equations (4.6) and (4.7) imply that

$$
\begin{gathered}
M_{1}+M_{2}+T f\left(\bar{x}_{1}, \bar{y}_{1}\right) \geq I(0, T, x) \\
=\int_{E} f\left(x(t), x^{\prime}(t)\right) d t+\int_{[0, T] \backslash E} f\left(x(t), x^{\prime}(t)\right) d t \\
\geq T f\left(\bar{x}_{1}, \bar{y}_{1}\right)+\delta \operatorname{mes}(E)
\end{gathered}
$$

and in view of (4.5),

$$
\operatorname{mes}(E) \leq \delta^{-1}\left(M_{1}+M_{2}\right) \leq L_{1}
$$

Assume that

$$
t \in\left[T_{1}, T_{2}\right] \backslash E
$$

By (4.7),

$$
f\left(x(t), x^{\prime}(t)\right) \leq f\left(\bar{x}_{1}, \bar{y}_{1}\right)+\delta .
$$

Combined with the choice of $\delta$ (see (4.3) and (4.4)) this implies that there exists $i \in\{1, \ldots, m\}$ such that

$$
\begin{gathered}
\left\|x(t)-\bar{x}_{i}\right\| \leq \varepsilon \\
\min \left\{\left\|x^{\prime}(t)+\bar{y}_{i}\right\|\left\|x^{\prime}(t)+\bar{y}_{i}\right\|\right\} \leq \varepsilon
\end{gathered}
$$

Theorem 4.1 is proved.

## 5. Auxilliary results

Analogously to Proposition 5.4 of [81] we can prove the following result.
Proposition 5.1. Let $\varepsilon, \Delta \in(0,1]$. Then there exist $\gamma \in\left(0,2^{-1} \Delta\right)$ and $\delta>0$ such that for each $k \in\{1, \ldots, m\}$ and each

$$
y, z \in B\left(\bar{x}_{k}, \boldsymbol{\delta}\right)
$$

there exists $\boldsymbol{\xi} \in W^{1,1}(0, \gamma)$ such that

$$
\begin{gathered}
\xi(0)=y, \xi(\gamma)=z, \\
I(0, \gamma, \xi) \leq \gamma f\left(\bar{x}_{k}, \bar{y}_{k}\right)+\varepsilon, \\
\left\|\xi(t)-\bar{x}_{k}\right\| \leq \varepsilon, t \in[0, \gamma], \\
B\left(\xi^{\prime}(t), \varepsilon\right) \cap\left\{\bar{y}_{k},-\bar{y}_{k}\right\} \neq \emptyset, t \in[0, \gamma] a . e . .
\end{gathered}
$$

Analogously to Proposition 5.5 of [81] we can prove the following result.
Proposition 5.2. Let $\varepsilon, \Delta \in(0,1]$. Then there exist $\gamma \in(0, \Delta)$ and $\delta>0$ such that for each $T>\gamma$, each $i \in\{1, \ldots, m\}$ and each

$$
y, z \in B\left(\bar{x}_{i}, \boldsymbol{\delta}\right)
$$

there exists $\xi \in W^{1,1}(0, T)$ such that

$$
\begin{gathered}
\xi(0)=y, \xi(T)=z, \\
I(0, T, \xi) \leq T f\left(\bar{x}_{i}, \bar{y}_{i}\right)+\varepsilon, \\
\left\|\xi(t)-\bar{x}_{t}\right\| \leq \varepsilon, t \in[0, T], \\
B\left(\xi^{\prime}(t), \varepsilon\right) \cap\left\{\bar{y}_{i},-\bar{y}_{i}\right\} \neq \emptyset, t \in[0, T] \text { a.e.. }
\end{gathered}
$$

Denote by $\mathfrak{M}$ the set of all borelian functions $g: X \times X \rightarrow R^{1}$ such that

$$
\begin{equation*}
g(x, u) \geq \psi(\|u\|)\|u\|-a \tag{5.1}
\end{equation*}
$$

(see (3.4) and (A3)) for each $(x, u) \in X \times X$.
The following result was obtained in [81] (Proposition 5.6).

Proposition 5.3. Let $M_{1}, \varepsilon>0$ and $0<\tau_{0}<\tau_{1}$. Then there exists $\delta>0$ such that for each pair of numbers $T_{1}, T_{2}$ satisfying

$$
0 \leq T_{1}, T_{2} \in\left[T_{1}+\tau_{0}, T_{1}+\tau_{1}\right]
$$

each $g \in \mathfrak{M}$, each $x \in W^{1,1}\left(T_{1}, T_{2}\right)$ satisfying

$$
\int_{T_{1}}^{T_{2}} g\left(x(t), x^{\prime}(t)\right) d t \leq M_{1}
$$

and each $t_{1}, t_{2} \in\left[T_{1}, T_{2}\right]$ satisfying $\left|t_{1}-t_{2}\right| \leq \delta$ the inequality

$$
\left\|x\left(t_{1}\right)-x\left(t_{2}\right)\right\| \leq \varepsilon
$$

holds.
Proposition 5.4. Let $\varepsilon, \Delta \in(0,1]$. Then there exist $\delta>0$ such that for each $k \in\{1, \ldots, m\}$, each $T \geq \Delta$ and each $\xi \in W^{1,1}(0, T)$ satisfying

$$
\begin{gather*}
\left\|\xi(0)-\bar{x}_{k}\right\| \leq \delta,\left\|\xi(T)-\bar{x}_{k}\right\| \leq \delta  \tag{5.2}\\
I(0, T, \xi) \leq U(0, T, \xi(0), \xi(T))+\delta \tag{5.3}
\end{gather*}
$$

the inequality

$$
\left\|\xi(t)-\bar{x}_{k}\right\| \leq \varepsilon
$$

holds for all $t \in[0, T]$.
Proof. We may assume without loss of generality that

$$
\begin{equation*}
\varepsilon<\min \left\{\left\|\bar{x}_{i}-\bar{x}_{j}\right\|: i, j \in\{1, \ldots, m\}, i<j\right\} / 8 . \tag{5.4}
\end{equation*}
$$

Proposition 5.3 implies that there exists

$$
\varepsilon_{0} \in(0, \min \{\varepsilon / 4, \Delta / 8\})
$$

such that the following property holds:
(a) for each pair of numbers $S_{1}, S_{2}$ satisfying

$$
0 \leq S_{1}, S_{2} \in\left[S_{1}+\Delta / 8, S_{1}+\Delta / 4\right]
$$

each $g \in \mathfrak{M}$, each $x \in W^{1,1}\left(S_{1}, S_{2}\right)$ satisfying

$$
\int_{S_{1}}^{S_{2}} g\left(x(t), x^{\prime}(t)\right) d t \leq 4^{-1} \Delta\left|f\left(\bar{x}_{1}, \bar{y}_{1}\right)\right|+1
$$

and each $t_{1}, t_{2} \in\left[S_{1}, S_{2}\right]$ satisfying $\left|t_{1}-t_{2}\right| \leq \varepsilon_{0}$ we have

$$
\left\|x\left(t_{1}\right)-x\left(t_{2}\right)\right\| \leq \varepsilon / 4
$$

By (A1) there exists $\varepsilon_{1} \in\left(0, \varepsilon_{0} / 4\right)$ such that the following property holds:
(b) for each $(x, y) \in X \times X$ satisfying

$$
f(x, y) \leq \inf (f)+\varepsilon_{1}
$$

there exists $i \in\{1, \ldots, m\}$ such that $\left\|x-\bar{x}_{i}\right\| \leq \varepsilon / 4$.
Proposition 5.2 implies that there exists

$$
\begin{equation*}
\delta \in\left(0, \varepsilon_{1}^{2} / 4\right) \tag{5.5}
\end{equation*}
$$

such that the following property holds:
(c) for each $T \geq \Delta$, each $i \in\{1, \ldots, m\}$ and each

$$
y, z \in B\left(\bar{x}_{i}, \boldsymbol{\delta}\right)
$$

there exists $\xi \in W^{1,1}(0, T)$ such that

$$
\begin{gathered}
\xi(0)=y, \xi(T)=z \\
I(0, T, \xi) \leq T f\left(\bar{x}_{i}, \bar{y}_{i}\right)+\varepsilon_{1}^{2} / 4
\end{gathered}
$$

Assume that $T \geq \Delta, \xi \in W^{1,1}(0, T), k \in\{1, \ldots, m\}$ and (64) holds, Property (c) and (5.3) imply that

$$
\begin{equation*}
U(0, T, \xi(0), \xi(T)) \leq T f\left(\bar{x}_{k}, \bar{y}_{k}\right)+\varepsilon_{1}^{2} / 4 . \tag{5.6}
\end{equation*}
$$

Equations (5.3)-(5.6) imply that

$$
\begin{equation*}
I(0, T, \xi) \leq T f\left(\bar{x}_{k}, \bar{y}_{k}\right)+\delta+\varepsilon_{1}^{2} / 4 \leq T f\left(\bar{x}_{k}, \bar{y}_{k}\right)+\varepsilon_{1}^{2} / 2 . \tag{5.7}
\end{equation*}
$$

In view of (5.7), for each set $E \subset[0, T]$,

$$
\begin{equation*}
\int_{E} f\left(\xi(t), \xi^{\prime}(t)\right) d t \leq \operatorname{mes}(E) f\left(\bar{x}_{k}, \bar{y}_{k}\right)+\varepsilon_{1}^{2} / 2 \tag{5.8}
\end{equation*}
$$

We show that for each $t \in[0, T]$,

$$
\begin{equation*}
\min \left\{\left\|\xi(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \varepsilon . \tag{5.9}
\end{equation*}
$$

Assume the contrary. Then there exists

$$
t_{0} \in[0, T]
$$

such that

$$
\begin{equation*}
\left\|\xi\left(t_{0}\right)-\bar{x}_{i}\right\|>\varepsilon, i=1, \ldots, m \tag{5.10}
\end{equation*}
$$

Clearly, there exists $a \in R^{1}$ satisfying

$$
\begin{equation*}
[a, a+\Delta / 4] \subset[0, T], t_{0} \in[a, a+\Delta / 4] . \tag{5.11}
\end{equation*}
$$

In view of (5.8),

$$
\begin{equation*}
I(a, a+\Delta / 4, \xi) \leq 4^{-1} \Delta f\left(\bar{x}_{k}, \bar{y}_{k}\right)+1 \tag{5.12}
\end{equation*}
$$

Property (a) and (5.12) imply that for each

$$
\begin{equation*}
t \in[a, a+\Delta / 4] \cap\left[t_{0}-\varepsilon, t_{0}+\varepsilon\right] \tag{5.13}
\end{equation*}
$$

and each $i \in\{1, \ldots, m\}$,

$$
\left\|\xi(t)-\xi\left(t_{0}\right)\right\| \leq \varepsilon / 4
$$

and

$$
\begin{equation*}
\left\|\xi(t)-\bar{x}_{i}\right\| \geq\left\|\xi\left(t_{0}\right)-\bar{x}_{i}\right\|-\left\|\xi(t)-\xi\left(t_{0}\right)\right\| \geq \varepsilon-\varepsilon / 4 \tag{5.14}
\end{equation*}
$$

Property (b), (5.13) and (5.14) imply that for each $t \in[a, a+\Delta / 4] \cap\left[t_{0}-\varepsilon, t_{0}+\varepsilon\right]$,

$$
\begin{equation*}
f\left(\xi(t), \xi^{\prime}(t)\right)>\inf (f)+\varepsilon_{1} \tag{5.15}
\end{equation*}
$$

By (5.71) and the inequality, $\varepsilon_{0}<\Delta / 8$,

$$
\begin{equation*}
\operatorname{mes}\left([a, a+\Delta / 4] \cap\left[t_{0}-\varepsilon, t_{0}+\varepsilon\right]\right) \geq \varepsilon_{0} . \tag{5.16}
\end{equation*}
$$

It follows from (5.11), (5.15) and (5.16) that

$$
\begin{aligned}
& I(0, T, \xi) \geq\left(\inf (f)+\varepsilon_{1}\right) \operatorname{mes}\left([a, a+\Delta / 4] \cap\left[t_{0}-\varepsilon, t_{0}+\varepsilon\right]\right) \\
& \quad+\inf (f) \operatorname{mes}\left([0, T] \backslash\left([a, a+\Delta / 4] \cap\left[t_{0}-\varepsilon, t_{0}+\varepsilon\right]\right)\right)
\end{aligned}
$$

$$
\geq \inf (f) T+\varepsilon_{0} \varepsilon_{1} \geq T \inf (f)+\varepsilon_{1}^{2}
$$

This contradicts (5.7). The contradiction we have reached proves that for each $t \in[0, T]$ (5.9) holds. We show that for each $t \in[0, T]$,

$$
\left\|\xi(t)-\bar{x}_{k}\right\| \leq \varepsilon
$$

Assume the contrary. Then there exists $S_{0} \in[0, T]$ such that

$$
\begin{equation*}
\left\|\xi\left(S_{0}\right)-\bar{x}_{k}\right\|>\varepsilon \tag{5.17}
\end{equation*}
$$

In view of (5.3), (5.4) and (5.17),

$$
S_{0} \in(0, T)
$$

Set

$$
\begin{equation*}
S_{1}=\sup \left\{\tau \in(0, T]:\left\|\xi(t)-\bar{x}_{k}\right\| \leq \varepsilon, t \in[0, T]\right\} \tag{5.18}
\end{equation*}
$$

Clearly, $S_{1}$ is well-defined,

$$
\begin{gather*}
S_{1}>0, S_{1}<S_{0}  \tag{5.19}\\
\left\|\xi(t)-\bar{x}_{k}\right\| \leq \varepsilon, t \in\left[0, S_{1}\right] . \tag{5.20}
\end{gather*}
$$

By (5.18)-(5.20), there exists a strictly decreasing sequence $\left\{\tau_{j}\right\}_{j=1}^{\infty}$ such that

$$
\begin{gather*}
\tau_{j} \in\left(S_{1}, T\right], j=1,2, \ldots, \lim _{j \rightarrow \infty} \tau_{j}=S_{1}  \tag{5.21}\\
\left\|\xi\left(\tau_{j}\right)-\bar{x}_{k}\right\|>\varepsilon, j=1,2, \ldots \tag{5.22}
\end{gather*}
$$

By (5.9), extracting a subsequence and re-indexing, we may assume without loss of generality that there exists $p \in\{1, \ldots, m\}$ such that

$$
\begin{equation*}
\left\|\xi\left(\tau_{j}\right)-\bar{x}_{p}\right\| \leq \varepsilon, p=1,2, \ldots \tag{5.23}
\end{equation*}
$$

In view of (5.22) and (5.23),

$$
\begin{equation*}
p \neq k \tag{5.24}
\end{equation*}
$$

Equations (5.21) and (5.23) imply that

$$
\left\|\xi\left(S_{1}\right)-\bar{x}_{p}\right\| \leq \varepsilon
$$

Together with (5.20) this implies that

$$
\left\|\bar{x}_{p}-\bar{x}_{k}\right\| \leq 2 \varepsilon .
$$

This contradicts (5.5) (see (5.24)). The contradiction we have reached proves that $\left\|\xi(t)-\bar{x}_{k}\right\| \leq$ $\varepsilon, t \in[0, T]$. Proposition 5.4 is proved.

## 6. A turnpike result

Now we state and prove our main result which give the full description of the structure of approximate solutions $u$ of our variational problems on an interval $[0, T]$ where $T$ is sufficiently large. It is shown that there are mutually disjoint subintervals $E_{i}, i=1, \ldots, q$ of $[0, T]$ where $q \leq$ $m$ and an injective mapping $p:\{1, \ldots, q\} \rightarrow\{1, \ldots, m\}$ such that the measure of the complement $[0, T] \backslash \cup_{i=1}^{q} E_{i}$ does not exceed a constant which does not depend on $T$ and for each $i \in\{1, \ldots, q\}$ the set $u\left(E_{i}\right)$ is contained in a small neighborhood of $\bar{x}_{p(i)}$.

Theorem 6.1. Let $M>0$ and $\varepsilon \in(0,1)$ satisfy

$$
\begin{equation*}
\varepsilon<\min \left\{\left\|\bar{x}_{i}-\bar{x}_{j}\right\|: i, j \in\{1, \ldots, m\}, i<j\right\} / 4 . \tag{6.1}
\end{equation*}
$$

Then there exist $L>0, \varepsilon_{1}, \delta \in(0, \varepsilon)$ such that for each $T>2 L$ and each $u \in W^{1,1}(0, T)$ such that

$$
\begin{equation*}
u(0) \in B(0, M) \tag{6.2}
\end{equation*}
$$

and at least of the following conditions holds:
(i)

$$
\begin{equation*}
u(T) \in B(0, M), I(0, T, u) \leq U(0, T, u(0), u(T))+\delta \tag{6.3}
\end{equation*}
$$

(ii)

$$
\begin{equation*}
I(0, T, u) \leq U(0, T, u(0))+\delta \tag{6.4}
\end{equation*}
$$

there exist an integer $q \geq 1$ and numbers $S_{i}, \tilde{S}_{i} \in[0, T], i=1, \ldots, q$ such that

$$
\begin{gather*}
S_{i} \leq \tilde{S}_{i}, i=1, \ldots, q, S_{i+1}>\tilde{S}_{i}, i \in\{1, \ldots, q\} \backslash\{q\}, \\
S_{i}<\tilde{S}_{i} \text { if } i \in\{1, \ldots, q\} \text { and } S_{i}<T \tag{6.5}
\end{gather*}
$$

and there exist $j_{1}, \ldots, j_{q} \in\{1, \ldots, m\}$ such that

$$
\begin{gather*}
j_{p_{1}} \neq j_{p_{2}} \text { for each } p, p_{2} \in\{1, \ldots, q\} \text { satisfying } p_{1} \neq p_{2},  \tag{6.6}\\
S_{1} \in[0, L], \min \left\{\left\|u\left(S_{1}\right)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta,
\end{gather*}
$$

for each $t \in\left[0, S_{1}\right)$,

$$
\min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\}>\delta
$$

for each $p \in\{1, \ldots, q\}$,

$$
\begin{gathered}
\left\|u\left(S_{p}\right)-\bar{x}_{j_{p}}\right\| \leq \delta, \\
\left\|u(t)-\bar{x}_{j_{p}}\right\| \leq \varepsilon, t \in\left[S_{p}, \tilde{S}_{p}\right], \\
\left\|u(t)-\bar{x}_{j_{p}}\right\|>\delta, t \in\left[\tilde{S}_{p}, S_{p}\right) \text { if } p>1, \\
\varepsilon_{1} \leq S_{p}-\tilde{S}_{p-1} \leq L \text { if } p>1, \\
\left\|u(t)-\bar{x}_{j_{p}}\right\|>\delta, t \in\left[\tilde{S}_{p}, T\right] \backslash\left\{\tilde{S}_{p}\right\}, \\
\text { if } S_{p}+\varepsilon_{1} \leq T \text { then } \tilde{S}_{p} \geq S_{p}+\varepsilon_{1}, \\
\text { if } S_{p}+\varepsilon_{1}>T \text { then } \tilde{S}_{p}=T, p=q, \\
\text { if } \tilde{S}_{p}<T \text { then }\left\|u\left(\tilde{S}_{p}\right)-\bar{x}_{j_{p}}\right\|=\varepsilon, \\
\tilde{S}_{q} \geq T-L, \\
\left\{t \in\left[\tilde{S}_{q}, T\right] \backslash\left\{\tilde{S}_{q}\right\}: \min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta\right\}=\emptyset .
\end{gathered}
$$

Proof. Theorem 3.2 implies that there exist $M_{0}>M$ such that

$$
\begin{equation*}
U(0, T, y, z) \leq T \inf (f)+M_{0} \tag{6.7}
\end{equation*}
$$

for each $T \geq 1$ and each $y, z \in B(0, M)$.
By Proposition 5.3 there exists

$$
\varepsilon_{1} \in(0, \varepsilon / 8)
$$

such that the following property holds:
(a) for each pair of numbers $S_{1}, S_{2}$ satisfying

$$
0 \leq S_{1}, S_{2} \in\left[S_{1}+4^{-1}, S_{1}+4\right]
$$

each $g \in \mathfrak{M}$, each $x \in W^{1,1}\left(S_{1}, S_{2}\right)$ satisfying

$$
\int_{S_{1}}^{S_{2}} g\left(x(t), x^{\prime}(t)\right) d t \leq 4|\inf (f)|+M_{0}+4
$$

and each $t_{1}, t_{2} \in\left[S_{1}, S_{2}\right]$ satisfying $\left|t_{1}-t_{2}\right| \leq \varepsilon_{1}$ the inequality

$$
\left\|x\left(t_{1}\right)-x\left(t_{2}\right)\right\| \leq \varepsilon / 8
$$

holds.
Proposition 5.4 implies that there exists $\delta \in\left(0, \varepsilon_{1} / 8\right)$ such that the following property holds:
(b) for each $k \in\{1, \ldots, m\}$, each $T \geq \varepsilon_{1} / 8$ and each $\xi \in W^{1,1}(0, T)$ satisfying

$$
\left\|\xi(0)-\bar{x}_{k}\right\| \leq \delta,\left\|\xi(T)-\bar{x}_{k}\right\| \leq \delta
$$

and

$$
I(0, T, \xi) \leq U(0, T, \xi(0), \xi(T))+\delta
$$

the inequality

$$
\left\|\xi(t)-\bar{x}_{k}\right\| \leq \varepsilon
$$

holds for all $t \in[0, T]$.
Theorem 4.1 implies that there exists $L>1$ such that the following property holds:
(c) for each $T>L$ and each $x \in W^{1,1}(0, T)$ such that

$$
x(0) \in B(0, M)
$$

and at least one of the following conditions holds:

$$
\begin{gathered}
x(T) \in B(0, M), I^{f}(0, T, x) \leq U(0, T, x(0), x(T))+1 \\
I^{f}(0, T, x) \leq U(0, T, x(0))+1
\end{gathered}
$$

the inequality

$$
\operatorname{mes}\left(\left\{t \in[0, T]:\left\|x(t)-\bar{x}_{i}\right\|>\delta \text { for each } i \in\{1, \ldots, m\}\right\}\right)<L
$$

is true.
Assume that $T \geq 2 L, u \in W^{1,1}(0, T)$, (6.2) is true and at least of conditions (i) and (ii) hold. Conditions (i), (ii) and (6.7) imply that

$$
\begin{equation*}
I(0, T, u) \leq T \inf (f)+M_{0}+1 \tag{6.8}
\end{equation*}
$$

In view of (6.8) for each measurable set $J \subset[0, T]$,

$$
\begin{equation*}
\int_{J} f\left(u(t), u^{\prime}(t)\right) d t \leq \operatorname{mes}(J) \inf (f)+M_{0}+1 \tag{6.9}
\end{equation*}
$$

Property (a) and (6.9) imply that for each $t_{1}, t_{2} \in[0, T]$ satisfying $\left|t_{1}-t_{2}\right| \leq \varepsilon_{1}$ we have

$$
\begin{equation*}
\left\|u\left(t_{1}\right)-u\left(t_{2}\right)\right\| \leq \varepsilon / 8 \tag{6.10}
\end{equation*}
$$

Property (c), conditions (i), (ii) and (6.2) imply that there exists a number $S_{1}$ such that

$$
\begin{equation*}
S_{1} \in[0, L], \min \left\{\left\|u\left(S_{1}\right)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta \tag{6.11}
\end{equation*}
$$

and that for each $t \in\left[0, S_{1}\right] \backslash\left\{S_{1}\right\}$,

$$
\begin{equation*}
\min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\}>\delta . \tag{6.12}
\end{equation*}
$$

By (6.1) and (6.11), there exists a unique integer $j_{1} \in\{1, \ldots, m\}$ such that

$$
\begin{equation*}
\left\|u\left(S_{1}\right)-\bar{x}_{j_{1}}\right\| \leq \delta \tag{6.13}
\end{equation*}
$$

In view of (6.11),

$$
\begin{equation*}
S_{1}+\varepsilon_{1} \leq 2 L \leq T \tag{6.14}
\end{equation*}
$$

It follows from (6.10), (6.11), (6.13) and (6.14) that for each $t \in\left[S_{1}, S_{1}+\varepsilon_{1}\right]$,

$$
\begin{gathered}
\left\|u(t)-u\left(S_{1}\right)\right\| \leq \varepsilon / 8 \\
\left\|u(t)-\bar{x}_{j_{1}}\right\| \leq\left\|u(t)-u\left(S_{1}\right)\right\|+\left\|u\left(S_{1}\right)-\bar{x}_{j_{1}}\right\| \leq \varepsilon / 8+\delta \leq \varepsilon
\end{gathered}
$$

and

$$
\begin{equation*}
\left\|u(t)-\bar{x}_{j_{1}}\right\| \leq \varepsilon, t \in\left[S_{1}, S_{1}+\varepsilon_{1}\right] \tag{6.15}
\end{equation*}
$$

Define

$$
\begin{equation*}
\tilde{S}_{1}=\sup \left\{\tau \in\left(S_{1}, T\right]:\left\|u(t)-\bar{x}_{j_{1}}\right\| \leq \varepsilon, t \in[0, \tau]\right\} \tag{6.16}
\end{equation*}
$$

By (6.15) and (6.16),

$$
\begin{equation*}
\tilde{S}_{1} \geq S_{1}+\varepsilon_{1},\left\|u\left(\tilde{S}_{1}\right)-\bar{x}_{j_{1}}\right\| \leq \varepsilon \tag{6.17}
\end{equation*}
$$

If $\tilde{S}_{1}=T$, then our construction is completed.
Assume that $\tilde{S}_{1}<T$. In view of (6.16),

$$
\begin{equation*}
\left\|u\left(\tilde{S}_{1}\right)-\bar{x}_{j_{1}}\right\|=\varepsilon \tag{6.18}
\end{equation*}
$$

Property (b), conditions (i), (ii) and equations (6.13) and (6.17) imply that for each $t \in\left(\tilde{S}_{1}, T\right]$,

$$
\begin{equation*}
\left\|u(t)-\bar{x}_{j_{1}}\right\|>\delta \tag{6.19}
\end{equation*}
$$

There are two cases:

$$
\begin{align*}
& \left\{t \in\left[\tilde{S}_{1}, T\right]: \min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta\right\}=\emptyset  \tag{6.20}\\
& \left\{t \in\left[\tilde{S}_{1}, T\right]: \min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta\right\} \neq \emptyset \tag{6.21}
\end{align*}
$$

If (6.20) holds, then property (c) and (6.17) imply that

$$
\tilde{S}_{1}+L \geq T
$$

and our construction is completed.
Assume that (6.21) holds. Set

$$
\begin{equation*}
S_{2}=\inf \left\{t \in\left[\tilde{S}_{1}, T\right]: \min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta\right\} \tag{6.22}
\end{equation*}
$$

Equations (6.1), (6.18) and (6.22) imply that

$$
S_{2}>\tilde{S}_{1}
$$

and there exists a unique $j_{2} \in\{1, \ldots, m\}$ such that

$$
\begin{equation*}
\left\|u\left(S_{2}\right)-\bar{x}_{j_{2}}\right\| \leq \delta \tag{6.23}
\end{equation*}
$$

By (6.19) and (6.23),

$$
j_{2} \neq j_{1},\left\|u\left(S_{2}\right)-\bar{x}_{j_{2}}\right\|=\delta
$$

It follows from (6.10), (6.16), (6.17), (6.22) and (6.23) that for every

$$
t \in[0, T] \cap\left[S_{2}-\varepsilon_{1}, S_{2}+\varepsilon_{1}\right]
$$

we have

$$
\begin{align*}
\left\|u(t)-\bar{x}_{j_{2}}\right\| & \leq\left\|u(t)-u\left(S_{2}\right)\right\|+\left\|u\left(S_{2}\right)-\bar{x}_{j_{2}}\right\| \\
& \leq \delta+\varepsilon / 8 \leq \varepsilon / 4 . \tag{6.24}
\end{align*}
$$

Equations (6.1), (6.17) and (6.24) imply that

$$
\begin{equation*}
\tilde{S}_{1} \leq S_{2}-\varepsilon_{1} \tag{6.25}
\end{equation*}
$$

If $S_{2}+\varepsilon_{1} \geq T$, then $\tilde{S}_{2}=T$ and our construction is completed. Otherwise we set

$$
\begin{equation*}
\tilde{S}_{2}=\inf \left\{S \in\left[S_{2}, T\right]:\left\|u(t)-\bar{x}_{j_{2}}\right\| \leq \varepsilon, t \in\left[S_{2}, S\right]\right\} \tag{6.26}
\end{equation*}
$$

Property (c), (6.22) and (6.26) imply that

$$
\begin{equation*}
S_{2}-\tilde{S}_{2} \leq L, S_{2}-\tilde{S}_{1} \leq L \tag{6.27}
\end{equation*}
$$

Assume that $k$ is an integer and we defined $S_{i}, \tilde{S}_{i} \in[0, T], i=1, \ldots, k$ such that $S_{i} \leq \tilde{S}_{i}, i=$ $1, \ldots, k$, if $S_{i}<T$, then $S_{i}<\tilde{S}_{i}$ for each $i \in\{1, \ldots, k\}$,

$$
S_{i+1}>\tilde{S}_{i}, i \in\{1, \ldots, k\} \backslash\{k\}
$$

and we defined $j_{1}, \ldots, j_{k} \in\{1, \ldots, m\}$ for which

$$
j_{p_{1}} \neq j_{p_{2}} \text { for each } p_{1}, p_{2} \in\{1, \ldots, k\} \text { satisfying } p_{1} \neq p_{2}
$$

and that (91)-(96) are true, for each $p \in\{1, \ldots, k\}$,

$$
\begin{gather*}
\left\|u\left(S_{p}\right)-\bar{x}_{j_{p}}\right\| \leq \delta,  \tag{6.28}\\
\left\|u(t)-\bar{x}_{j_{p}}\right\| \leq \varepsilon, t \in\left[S_{p}, \tilde{S}_{p}\right],  \tag{6.29}\\
\left\|u(t)-\bar{x}_{j_{p}}\right\|>\delta, t \in\left[\tilde{S}_{p-1}, S_{p}\right) \text { if } p>1,  \tag{6.30}\\
\varepsilon_{1} \leq S_{p}-\tilde{S}_{p-1} \leq L \text { if } p>1,  \tag{6.31}\\
\left\|u(t)-\bar{x}_{j_{p}}\right\|>\delta, t \in\left[\tilde{S}_{p}, T\right] \backslash\left\{\tilde{S}_{p}\right\},  \tag{6.32}\\
\text { if } S_{p}+\varepsilon_{1} \leq T \text { then } \tilde{S}_{p} \geq S_{p}+\varepsilon_{1},  \tag{6.33}\\
\text { if } S_{p}+\varepsilon_{1}>T \text { then } \tilde{S}_{p}=T, p=k,  \tag{6.34}\\
\text { if } S_{p}<T \text { then }\left\|u\left(\tilde{S}_{p}\right)-\bar{x}_{j_{p}}\right\|=\varepsilon . \tag{6.35}
\end{gather*}
$$

(It is not difficult to see that for $k=1$ our assumption holds.)
If $\tilde{S}_{k}=T$, then our construction is completed. Assume that $\tilde{S}_{k}<T$. There are two cases:

$$
\begin{align*}
& \left\{t \in\left[\tilde{S}_{k}, T\right]: \min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta\right\}=\emptyset  \tag{6.36}\\
& \left\{t \in\left[\tilde{S}_{k}, T\right]: \min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta\right\} \neq \emptyset \tag{6.37}
\end{align*}
$$

If (6.36) holds, then property (c), conditions (i), (ii) and (6.29) imply that

$$
\tilde{S}_{k}+L \geq T
$$

and our construction is completed.
Assume that (6.37) holds. Set

$$
\begin{equation*}
S_{k+1}=\inf \left\{t \in\left[\tilde{S}_{k}, T\right]: \min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta\right\} . \tag{6.38}
\end{equation*}
$$

Equations (6.35), (6.37) and (6.38) imply that

$$
S_{k+1}>\tilde{S}_{k}
$$

and there exists a unique $j_{k+1} \in\{1, \ldots, m\}$ such that

$$
\begin{equation*}
\left\|u\left(S_{k+1}\right)-\bar{x}_{j_{k+1}}\right\| \leq \delta \tag{6.39}
\end{equation*}
$$

By (6.32) and (6.39),

$$
j_{k+1} \neq j_{p}, p=1, \ldots, k
$$

By (6.10) and (6.38), for every

$$
t \in[0, T] \cap\left[S_{k+1}-\varepsilon_{1}, S_{k+1}+\varepsilon_{1}\right]
$$

we have

$$
\begin{gather*}
\left\|u(t)-\bar{x}_{j_{k+1}}\right\| \leq\left\|u(t)-u\left(S_{k+1}\right)\right\|+\left\|u\left(S_{k+1}\right)-\bar{x}_{j_{k+1}}\right\| \\
\leq \delta+\varepsilon / 8 \leq \varepsilon / 4 . \tag{6.40}
\end{gather*}
$$

It follows from (6.1), (6.35) and (6.40),

$$
\tilde{S}_{k} \leq S_{k+1}-\varepsilon_{1}
$$

If $S_{k+1}+\varepsilon_{1} \geq T$, then $\tilde{S}_{k+1}=T$ and our construction is completed. Otherwise we set

$$
\begin{equation*}
\tilde{S}_{k+1}=\inf \left\{S \in\left[\tilde{S}_{k+1}, T\right]:\left\|u(t)-\bar{x}_{j_{k+1}}\right\| \leq \varepsilon, t \in\left[S_{k+1}, S\right]\right\} \tag{6.41}
\end{equation*}
$$

Property (b), (6.37)-(6.41), (6.41) and equations above imply that the assumption made for $k$ also holds for $k+1$. Therefore by induction we constructed an integer $q \geq 1$, numbers $S_{i}, \tilde{S}_{i} \in$ $[0, T], i=1, \ldots, q$ such that $S_{i} \leq \tilde{S}_{i}, i=1, \ldots, q$, if $S_{i}<T$, then $S_{i}<\tilde{S}_{i}$ for each $i \in\{1, \ldots, q\}$,

$$
S_{i+1}>\tilde{S}_{i}, i \in\{1, \ldots, q\} \backslash\{q\}
$$

and we defined $j_{1}, \ldots, j_{q} \in\{1, \ldots, m\}$ for which

$$
j_{p_{1}} \neq j_{p_{2}} \text { for each } p_{1}, p_{2} \in\{1, \ldots, q\} \text { satisfying } p_{1} \neq p_{2}
$$

and that (6.11)-(6.16) are true, for each $p \in\{1, \ldots, q\}$, (6.28)-(6.35) hold (with $p=q$ ),

$$
\begin{gathered}
\tilde{S}_{q} \geq T-L \\
\left\{t \in\left[\tilde{S}_{q}, T\right]: \min \left\{\left\|u(t)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta\right\}=\emptyset
\end{gathered}
$$

Theorem 6.1 is proved.

## 7. The second turnpike result

Theorem 10 describes the structure of $M$-approximate solutions $u$ of our variational problems on an interval $[0, T]$ where $T$ is sufficiently large and $M>0$ is sufficiently small. Our next solutions is related to the case when $M$ is fixed but not necessarily small. It is shown that there are mutually disjoint subintervals $E_{i}, i=1, \ldots, q$ of $[0, T]$ where $q$ does not exceed a constant which does not depend on $T$ and a mapping $p:\{1, \ldots, q\} \rightarrow\{1, \ldots, m\}$ (not necessarily injective) such that the measure of the complement $[0, T] \backslash \cup_{i=1}^{q} E_{i}$ does not exceed a constant which does not depend on $T$ and for each $i \in\{1, \ldots, q\}$ the set $u\left(E_{i}\right)$ is contained in a small neighborhood of $\bar{x}_{p(i)}$.
Theorem 7.1. Let $\varepsilon \in(0,1], M_{1}>0$ and $M_{0}>\left\|\bar{x}_{i}\right\|+\left\|\bar{y}_{i}\right\|+1, i=1, \ldots, m$. Then there exist $l>0$ and a natural number $Q$ such that for each $T>l Q$ and each $x \in W^{1,1}(0, T)$ such that

$$
\begin{equation*}
\|x(0)\| \leq M_{0} \tag{7.1}
\end{equation*}
$$

and at least one of the following conditions holds:
(a)

$$
\|x(T)\| \leq M_{0}, I(0, T, x) \leq U(0, T, x(0), x(T))+M_{1}
$$

(b)

$$
I(0, T, x) \leq U(0, T, x(0))+M_{1}
$$

there exist an integer $q \in[1, Q]$ and intervals $\left[a_{i}, b_{i}\right] \subset[0, T], i=1, \ldots, q$ such that

$$
a_{i+1} \geq b_{i}, i \in\{1, \ldots, q\} \backslash\{q\}
$$

for each $i \in\{1, \ldots, q\}$, there exists $p_{i} \in\{1, \ldots, m\}$, such that

$$
\left\|x(t)-\bar{x}_{p_{i}}\right\| \leq \varepsilon, t \in\left[a_{i}, b_{i}\right]
$$

and

$$
\operatorname{mes}\left([0, T] \backslash \cup_{i=1}^{q}\left[a_{i}, b_{i}\right]\right) \leq l
$$

Proof. Theorem 6.1 implies that there exist $L_{0}>0, \delta>0$ such that the following property holds:
(c) for each $T>2 L_{0}$ and each $u \in W^{1,1}(0, T)$ such that

$$
\begin{gathered}
u(0), u(T) \in B\left(0, M_{0}\right) \\
I(0, T, u) \leq U(0, T, u(0), u(T))+\delta
\end{gathered}
$$

there exist an integer $q \in\{1, \ldots, m\}$ and numbers $S_{i}, \tilde{S}_{i} \in[0, T], i=1, \ldots, q$ such that

$$
\begin{gathered}
S_{i} \leq \tilde{S}_{i}, i=1, \ldots, q, S_{i+1}>\tilde{S}_{i}, i \in\{1, \ldots, q\} \backslash\{q\}, \\
S_{i}<\tilde{S}_{i} \text { if } i \in\{1, \ldots, q\} \text { and } S_{i}<T
\end{gathered}
$$

and there exist $j_{1}, \ldots, j_{q} \in\{1, \ldots, m\}$ such that

$$
\begin{aligned}
S_{1} & \leq L_{0}, \tilde{S}_{q} \geq T-L_{0} \\
S_{p}-\tilde{S}_{p-1} & \leq L_{0}, p \in\{1, \ldots, q\} \backslash\{1\} \\
\left\|u(t)-\bar{x}_{j_{p}}\right\| & \leq \varepsilon, t \in\left[S_{p}, \tilde{S}_{p}\right], p=1, \ldots, q
\end{aligned}
$$

Theorem 4.1 implies that there exists $L_{1}>2 L_{0}$ such that the following property holds:
(d) for each $T \geq L_{1}$ and each $x \in W^{1,1}(0, T)$ such that $x(0) \in B\left(0, M_{0}\right)$ and at least one of the following conditions holds:

$$
\begin{gathered}
x(T) \in B\left(0, M_{0}\right), I^{f}(0, T, x) \leq U(0, T, x(0), x(T))+M_{1}+1 ; \\
I^{f}(0, T, x) \leq U(0, T, x(0))+M_{1}
\end{gathered}
$$

the inequality

$$
\operatorname{mes}\left(\left\{t \in[0, T]:\left\|x(t)-\bar{x}_{i}\right\|>\delta \text { for each } i \in\{1, \ldots, m\}\right\}\right)<L_{1}
$$

Fix

$$
\begin{equation*}
l_{0}=4 L_{1}+4, l>4 Q l_{0} \tag{7.2}
\end{equation*}
$$

Choose an integer

$$
\begin{equation*}
Q>2 m\left(4+\delta^{-1} M_{1}\right) \tag{7.3}
\end{equation*}
$$

Assume that $T>l Q$ and that $x \in W^{1,1}(0, T)$ satisfies at least one of conditions (a) and (b). Together with property (d) this implies that there exists

$$
\begin{equation*}
t_{0} \in\left[0, L_{1}\right] \tag{7.4}
\end{equation*}
$$

such that

$$
\begin{equation*}
\min \left\{\left\|x\left(t_{0}\right)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta \tag{7.5}
\end{equation*}
$$

Property (d), conditions (a), (b) and equations (7.1), (7.4) and (7.5) imply that there exists a finite sequence of numbers $t_{0}<t_{1} \cdots<t_{q}$ belonging to the interval $[0, T]$ such that for each $k \in\{0, \ldots, q\}$,

$$
\begin{gather*}
\min \left\{\left\|x\left(t_{k}\right)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta,  \tag{7.6}\\
t_{i+1}-t_{i} \in\left[L_{1}, 2 L_{1}\right], i \in\{0, \ldots, q\} \backslash\{q\}  \tag{7.7}\\
t_{q}>T-2 L_{1} \tag{7.8}
\end{gather*}
$$

Now we construct a strictly increasing sequence of numbers $S_{i} \in\left\{t_{0}, \ldots, t_{q}\right\}, i=0, \ldots, p$. Set

$$
\begin{equation*}
S_{0}=t_{0} . \tag{7.9}
\end{equation*}
$$

Assume that $k \geq 0$ is an integer and that we already defined a finite increasing sequence $S_{i} \in$ $\left\{t_{0}, \ldots, t_{q}\right\}, i=0, \ldots, k$. If $S_{k}=t_{q}$, then the construction is completed. Assume that

$$
\begin{equation*}
S_{k}<t_{q} . \tag{7.10}
\end{equation*}
$$

If

$$
I\left(S_{k}, t_{q}, x\right) \leq U\left(S_{k}, t_{q}, x\left(S_{k}\right), x\left(t_{q}\right)\right)+\delta
$$

then we set

$$
S_{k+1}=t_{q}
$$

and the construction is completed. Assume that

$$
\begin{equation*}
I\left(S_{k}, t_{q}, x\right)>U\left(S_{k}, t_{q}, x\left(S_{k}\right), x\left(t_{q}\right)\right)+\delta \tag{7.11}
\end{equation*}
$$

There exists $j \in\{0, \ldots, q\}$ such that

$$
\begin{equation*}
S_{k}=t_{j} \tag{7.12}
\end{equation*}
$$

If

$$
I\left(S_{k}, t_{j+1}, x\right)>U\left(S_{k}, t_{j+1}, x\left(S_{k}\right), x\left(t_{j+1}\right)\right)+\delta
$$

then we set

$$
S_{k+1}=t_{j+1}
$$

Assume that

$$
\begin{equation*}
I\left(S_{k}, t_{j+1}, x\right) \leq U\left(S_{k}, t_{j+1}, x\left(S_{k}\right), x\left(t_{j+1}\right)\right)+\delta . \tag{7.13}
\end{equation*}
$$

We define

$$
\begin{gather*}
S_{k+1}=\min \left\{t_{i}: i \in\{j+1, \ldots, q\}:\right. \\
\left.I\left(S_{k}, t_{i}, x\right)>U\left(S_{k}, t_{i}, x\left(S_{k}\right), x\left(t_{i}\right)\right)+\delta\right\} \tag{7.14}
\end{gather*}
$$

Therefore by induction we defined a strictly increasing sequence of numbers

$$
S_{i} \in\left\{t_{0}, \ldots, t_{q}\right\}, i=0, \ldots, p
$$

such that

$$
S_{0}=t_{0}, S_{p}=t_{q},
$$

for each $j \in\{0, \ldots, p-1\} \backslash\{p-1\}$,

$$
\begin{equation*}
I\left(S_{j}, S_{j+1}, x\right)>U\left(S_{j}, S_{j+1}, x\left(S_{j}\right), x\left(S_{j+1}\right)\right)+\delta \tag{7.15}
\end{equation*}
$$

for each $j \in\{0, \ldots, p-1\}$, if $i \in\{0, \ldots, q\}$ and

$$
S_{j}<t_{i}<S_{j+1}
$$

then

$$
\begin{equation*}
I\left(S_{j}, t_{i}, x\right) \leq U\left(S_{j}, t_{i}, x\left(S_{j}\right), x\left(t_{i}\right)\right)+\delta, \tag{7.16}
\end{equation*}
$$

Conditions (a), (b) and (7.15) imply that

$$
\begin{gathered}
M_{1} \geq I(0, T, x)-U(0, T, x(0), x(T)) \\
\geq \sum\left\{I\left(S_{j}, S_{j+1}, x\right)-U\left(S_{j}, S_{j+1}, x\left(S_{j}\right), x\left(S_{j+1}\right)\right): j \in\{0, \ldots, p-1\} \backslash\{p-1\}\right\} \\
\geq(p-1) \delta
\end{gathered}
$$

and

$$
\begin{equation*}
p \leq 1+\delta^{-1} M_{1} \tag{7.17}
\end{equation*}
$$

Assume that $j \in\{0, \ldots, p-1\}$ satisfies

$$
\begin{equation*}
S_{j+1}-S_{j} \geq l_{0} \tag{7.18}
\end{equation*}
$$

Property (d), conditions (a) and (b) and equations (7.2), (7.6), (7.14) and (7.18) imply that there exists

$$
\begin{equation*}
\tilde{S}_{j} \in\left[S_{j+1}-3 L_{1}, S_{j+1}-2 L_{1}\right] \tag{7.19}
\end{equation*}
$$

such that

$$
\begin{equation*}
\min \left\{\left\|x\left(\tilde{S}_{j}\right)-\bar{x}_{i}\right\|: i=1, \ldots, m\right\} \leq \delta \tag{7.20}
\end{equation*}
$$

It follows from (7.7), (7.16) and (7.19) that

$$
\begin{equation*}
I\left(S_{j}, \tilde{S}_{j}, x\right) \leq U\left(S_{j}, \tilde{S}_{j}, x\left(S_{j}\right), x\left(\tilde{S}_{j}\right)\right)+\delta \tag{7.21}
\end{equation*}
$$

Property (c) and equations (7.2), (7.18)-(7.21) imply that there exist an integer $q_{j} \geq 1$ and numbers $S_{j, i}, \tilde{S}_{j, i} \in\left[S_{j}, \tilde{S}_{j}\right], i=1, \ldots, q_{j}$ such that

$$
\begin{gathered}
S_{j, i} \leq \tilde{S}_{j, i}, i=1, \ldots, q_{j}, S_{j, i+1}>\tilde{S}_{j, i}, i \in\left\{1, \ldots, q_{j}\right\} \backslash\left\{q_{j}\right\}, \\
S_{j, i}<\tilde{S}_{j, i} \text { if } i \in\left\{1, \ldots, q_{j}\right\} \text { and } S_{j, i}<T
\end{gathered}
$$

and there exist $k_{j, 1}, \ldots, k_{j, q_{j}} \in\{1, \ldots, m\}$ such that

$$
\begin{gathered}
S_{j, 1} \leq L_{0}+S_{j}, \tilde{S}_{j, q_{j}} \geq \tilde{S}_{j}-L_{0} \\
S_{j, p}-\tilde{S}_{j, p-1} \leq L_{0}, j \in\left\{1, \ldots, q_{j}\right\} \backslash\{1\}
\end{gathered}
$$

$$
\left\|u(t)-\bar{x}_{j, k_{\tau}}\right\| \leq \varepsilon, t \in\left[S_{j, \tau}, \tilde{S}_{j, \tau}\right], \tau=1, \ldots, q_{j}
$$

Consider the collection of intervals $\left[S_{j, \tau}, \tilde{S}_{j, \tau}\right], \tau=1, \ldots, q_{j}, j \in\{0, \ldots, p-1\}$ such that $S_{j+1}-$ $S_{j} \geq l_{0}$. The number of these intervals does not exceed ( $p+2$ ) $m<Q$ (see (7.2) and (7.17)). The completion of their union in $[0, T]$ is also a union of a finite collection of subintervals of $[0, T]$ and in view of (7.3), (7.17) their number does not exceed

$$
2(p+2) m \leq 2 m\left(4+\delta^{-1} M_{1}\right)<Q
$$

By (7.2), (7.4) and (7.8) the measure of this complement does not exceed

$$
Q l_{0}+3 Q L_{1}+3 L_{1}<Q l_{0}+3(Q+1) L_{1}<l .
$$

Theorem 7.1 is proved.

## REFERENCES

[1] B. D. O. Anderson, J. B. Moore, Linear optimal control, Prentice-Hall, Englewood Cliffs, NJ 1971.
[2] V. I. Arkin, I. V. Evstigneev, Stochastic models of control and economic dynamics, Academic Press, London, 1987.
[3] S. M. Aseev, M. I. Krastanov, V. M. Veliov, Optimality conditions for discrete-time optimal control on infinite horizon, Pure and Applied Functional Analysis 2 (2017) 395-409.
[4] S. M. Aseev, V. M. Veliov, Maximum principle for infinite-horizon optimal control problems with dominating discount, Dynamics Contin. Discrete Impuls. Syst., Series B 19 (2012) 43-63.
[5] S. Aubry, P. Y. Le Daeron, The discrete Frenkel-Kontorova model and its extensions I, Physica D 8 (1983) 381-422.
[6] M. Bachir, J. Blot, Infinite dimensional infinite-horizon Pontryagin principles for discrete-time problems, Set-Valued and Variational Analysis 23 (2015) 43-54.
[7] M. Bachir, J. Blot, Infinite dimensional multipliers and Pontryagin principles for discrete-time problems, Pure and Applied Functional Analysis 2 (2017) 411-426.
[8] V. Barbu, T. Precupanu, Convexity and optimization in Banach spaces, Springer Monographs in Mathematics, Springer Dordrecht Heidelberg London New York 2012.
[9] M. Bardi, On differential games with long-time-average cost, Advances in Dynamic Games and their Applications, Birkhauser (2009) 3-18.
[10] J. Baumeister, A. Leitao, G. N. Silva, On the value function for nonautonomous optimal control problem with infinite horizon, Syst. Control Lett. 56 (2007) 188-196.
[11] J. Blot, Infinite-horizon Pontryagin principles without invertibility, J. Nonlinear Convex Anal. 10 (2009) 177-189.
[12] J. Blot, P. Cartigny, Optimality in infinite-horizon variational problems under sign conditions, J. Optim. Theory Appl. 106 (2000) 411-419.
[13] J. Blot, N. Hayek, Sufficient conditions for infinite-horizon calculus of variations problems, ESAIM Control Optim. Calc. Var. 5 (2000) 279-292.
[14] J. Blot N. Hayek, Infinite-horizon optimal control in the discrete-time framework, SpringerBriefs in Optimization, New York 2014.
[15] D. A. Carlson, The existence of catching-up optimal solutions for a class of infinite horizon optimal control problems with time delay, SIAM Journal on Control and Optimization 28 (1990) 402-422.
[16] D. A. Carlson, A. Haurie, A. Leizarowitz, Infinite horizon optimal control, Berlin, Springer-Verlag, 1991.
[17] B. D. Coleman, M. Marcus, V. J. Mizel, On the thermodynamics of periodic phases, Arch. Rational Mech. Anal. 117 (1992) 321-347.
[18] T. Damm, L. Grune, M. Stieler, K. Worthmann, An exponential turnpike theorem for dissipative discrete time optimal control problems, SIAM Journal on Control and Optimization 52 (2014) 1935-1957.
[19] V. A. De Oliveira, G. N. Silva, Optimality conditions for infinite horizon control problems with state constraints, Nonlinear Analysis 71 (2009) 1788-1795.
[20] I. V. Evstigneev, S. D. Flam, Rapid growth paths in multivalued dynamical systems generated by homogeneous convex stochastic operators, Set-Valued Anal. 6 (1998) 61-81.
[21] V. Gaitsgory, L. Grune, N. Thatcher, Stabilization with discounted optimal control, Systems and Control Letters 82 (2015) 91-98.
[22] V. Gaitsgory, M. Mammadov, L. Manic, On stability under perturbations of long-run average optimal control problems, Pure and Applied Functional Analysis 2 (2017), 461-476.
[23] V. Gaitsgory, A. Parkinson, I. Shvartsman, Linear programming formulations of deterministic infinite horizon optimal control problems in discrete time, Discrete Contin. Dyn. Syst. Ser. B 22 (2017) 3821-3838.
[24] V. Gaitsgory, S. Rossomakhine, N. Thatcher, Approximate solution of the HJB inequality related to the infinite horizon optimal control problem with discounting, Dynamics Contin. Discrete Impuls. Syst., Series B, 19 (2012) 65-92.
[25] D. Gale, On optimal development in a multi-sector economy, Rev. Econ. Stud. 34 (1967) 1-18.
[26] V. Y. Glizer, O. Kelis, Upper value of a singular infinite horizon zero-sum linear-quadratic differential game, Pure and Applied Functional Analysis 2 (2017) 511-534.
[27] L. Grune, R. Guglielmi, Turnpike properties and strict dissipativity for discrete time linear quadratic optimal control problems, SIAM J. Control Optim. 56 (2018) 1282-1302.
[28] M. Gugat, A turnpike result for convex hyperbolic optimal boundary control problems, Pure and Applied Functional Analysis 4 (2019) 849-866.
[29] M. Gugat, F. M. Hante, On the turnpike phenomenon for optimal boundary control problems with hyperbolic systems, SIAM J. Control Optim. 57 (2019) 264-289.
[30] M. Gugat, E. Trelat, E. Zuazua, Optimal Neumann control for the 1D wave equation: finite horizon, infinite horizon, boundary tracking terms and the turnpike property, Systems Control Lett. 90 (2016) 61-70.
[31] X. Guo, O. Hernandez-Lerma, Zero-sum continuous-time Markov games with unbounded transition and discounted payoff rates, Bernoulli 11 (2016) 1009-1029.
[32] J. Hannon, M. Marcus, V. J. Mizel, A variational problem modelling behavior of unorthodox silicon crystals, ESAIM Control Optim. Calc. Var. 9 (2003) 145-149.
[33] N. Hayek, Infinite horizon multiobjective optimal control problems in the discrete time case, Optimization 60 (2011) 509-529.
[34] O. Hernandez-Lerma, J. B. Lasserre, Zero-sum stochastic games in Borel spaces: average payoff criteria, SIAM J. Control Optim 39 (2001) 1520-1539.
[35] N. V. Hritonenko, Yu. Yatsenko, Turnpike theorems in an integral dynamic model of economic restoration, Cybernet. Systems Anal. 33 (1997) 259-273.
[36] N. Hritonenko, Yu. Yatsenko, Turnpike and optimal trajectories in integral dynamic models with endogenous delay, J. Optim. Theory Appl. 127 (2005) 109-127.
[37] H. Jasso-Fuentes, O. Hernandez-Lerma, Characterizations of overtaking optimality for controlled diffusion processes, Appl. Math. Optim. 57 (2008) 349-369.
[38] M. A. Khan, A. J. Zaslavski, On two classical turnpike results for the Robinson-Solow-Srinivisan (RSS) model, Adv. in Math. Econom. 13 (2010) 47-97.
[39] D. V. Khlopin, Necessity of vanishing shadow price in infinite horizon control problems, J. Dyn. Control. Syst. 19 (2013) 519-552.
[40] D. V. Khlopin, On Lipschitz continuity of value functions for infinite horizon problem, Pure and Applied Functional Analysis 2 (2017) 535-552.
[41] V. Kolokoltsov, W. Yang, The turnpike theorems for Markov games, Dynamic Games and Applications 2 (2012) 294-312.
[42] A. Leizarowitz, Infinite horizon autonomous systems with unbounded cost, Appl. Math. and Opt. 13 (1985) 19-43.
[43] A. Leizarowitz, V. J. Mizel, One dimensional infinite horizon variational problems arising in continuum mechanics, Arch. Rational Mech. Anal. 106 (1989) 161-194.
[44] X. Li, J. Yong, Optimal control theory for infinite dimensional systems. Birkhauser, Boston Basel Berlin, 1995.
[45] V. Lykina, S. Pickenhain, M. Wagner, Different interpretations of the improper integral objective in an infinite horizon control problem, J. Math. Anal. Appl. 340 (2008) 498-510.
[46] V. L. Makarov, A. M. Rubinov, Mathematical theory of economic dynamics and equilibria, Springer-Verlag, New York, 1977.
[47] A. B. Malinowska, N. Martins, D. F. M. Torres, Transversality conditions for infinite horizon variational problems on time scales, Optimization Lett. 5 (2011) 41-53.
[48] M. Mammadov, Turnpike theorem for an infinite horizon optimal control problem with time delay, SIAM Journal on Control and Optimization 52 (2014) 420-438.
[49] M. Marcus, A. J. Zaslavski, On a class of second order variational problems with constraints, Israel J. Math. 111 (1999) 1-28.
[50] M. Marcus, A. J. Zaslavski, The structure of extremals of a class of second order variational problems, Ann. Inst. H. Poincaré, Anal. non linéaire 16 (1999) 593-629.
[51] M. Marcus, A. J. Zaslavski, The structure and limiting behavior of locally optimal minimizers, Ann. Inst. H. Poincaré, Anal. non linéaire, 19 (2002) 343-370.
[52] L. W. McKenzie, Turnpike theory, Econometrica 44 (1976) 841-866.
[53] V. J. Mizel, A. J. Zaslavski, Anisotropic functions: a genericity result with crystallographic implications, ESAIM: Control, Optimization and the Calculus of Variations 10 (2004) 624-633.
[54] B. S. Mordukhovich, Optimal control and feedback design of state-constrained parabolic systems in uncertainly conditions, Appl. Analysis 90 (2011) 1075-1109.
[55] B. S. Mordukhovich, I. Shvartsman, Optimization and feedback control of constrained parabolic systems under uncertain perturbations, Optimal control, stabilization and nonsmooth analysis. Lecture Notes Control Inform. Sci., Springer (2004), 121-132.
[56] S. Pickenhain, V. Lykina, M. Wagner, On the lower semicontinuity of functionals involving Lebesgue or improper Riemann integrals in infinite horizon optimal control problems, Control Cybernet. 37 (2008) 451468.
[57] A. Porretta, E. Zuazua, Long time versus steady state optimal control, SIAM J. Control Optim. 51 (2013) 4242-4273.
[58] T. Prieto-Rumeau, O. Hernandez-Lerma, Bias and overtaking equilibria for zero-sum continuous-time Markov games, Math. Methods Oper. Res. 61 (2005) 437-454.
[59] N. Sagara, Recursive variational problems in nonreflexive Banach spaces with an infinite horizon: an existence result, Discrete Contin. Dyn. Syst. Ser. S 11 (2018) 1219-1232.
[60] P. A. Samuelson, A catenary turnpike theorem involving consumption and the golden rule, Amer. Econom. Rev. 55 (1965) 486-496.
[61] K. E. Semenov, N. V. Hritonenko, Yu. Yatsenko, Turnpike properties of the optimal periods of the service of funds, Dokl. Akad. Nauk Ukrainy 173 (1992) 76-80.
[62] E. Trelat, C. Zhang, E. Zuazua, Optimal shape design for 2D heat equations in large time, Pure and Applied Functional Analysis 3 (2018) 255-269.
[63] E. Trelat, C. Zhang, E. Zuazua, Steady-state and periodic exponential turnpike property for optimal control problems in Hilbert spaces, SIAM J. Control Optim. 56 (2018) 1222-1252.
[64] C. C. von Weizsacker, Existence of optimal programs of accumulation for an infinite horizon, Rev. Econ. Studies 32 (1965) 85-104.
[65] A. J. Zaslavski, Ground states in Frenkel-Kontorova model, Math. USSR Izvestiya 29 (1987) 323-354.
[66] A. J. Zaslavski, Turnpike properties in the calculus of variations and optimal control, Springer, New York, 2006.
[67] A. J. Zaslavski, A porosity result for variational problems arising in crystallography, Communications in Applied Analysis 10 (2006) 537-548.
[68] A. J. Zaslavski, The existence and structure of approximate solutions of dynamic discrete time zero-sum games, Journal of Nonlinear and Convex Analysis 12 (2011) 49-68.
[69] A. J. Zaslavski, Nonconvex optimal control and variational problems, Springer Optimization and Its Applications, New York, 2013.
[70] A. J. Zaslavski, Structure of approximate solutions of optimal control problems, SpringerBriefs in Optimization, New York, 2013.
[71] A. J. Zaslavski, Turnpike phenomenon and infinite horizon optimal control, Springer Optimization and Its Applications, New York, 2014.
[72] A. J. Zaslavski, Turnpike theory for dynamic zero-sum games, Proceedings of the workshop "Variational and optimal control problems on unbounded domains", Haifa, 2012, Contemporary Mathematics: 619 (2014) 225-247.
[73] A. J. Zaslavski, Turnpike properties of approximate solutions of dynamic discrete time zero-sum games, Journal of Dynamics and Games 2014 (2014) 299-330.
[74] A. J. Zaslavski, Stability of the turnpike phenomenon in discrete-time optimal control problems, SpringerBriefs in Optimization, New York, 2014.
[75] A. J. Zaslavski, Turnpike theory of continuous-time linear optimal control problems, Springer Optimization and Its Applications, Cham-Heidelberg-New York-Dordrecht-London, 2015.
[76] A. J. Zaslavski, Structure of solutions of optimal control problems on large intervals: a survey of recent results, Pure and Applied Functional Analysis 1 (2016) 123-158.
[77] A. J. Zaslavski, Linear control systems with nonconvex integrands on large intervals, Pure and Applied Functional Analysis 1 (2016) 441-474.
[78] A. J. Zaslavski, Bolza optimal control problems with linear equations and nonconvex integrands on large intervals, Pure and Applied Functional Analysis 2 (2017) 153-182.
[79] A. J. Zaslavski, Discrete-time optimal control and games on large intervals, Springer Optimization and Its Applications, Springer, 2017.
[80] A. J. Zaslavski, Turnpike conditions in infinite dimensional optimal control, Springer Optimization and Its Applications, Springer, 2019.
[81] A. J. Zaslavski, Turnpike phenomenon and symmetric optimization problems, Springer Optimization and Its Applications, Springer, 2022.


[^0]:    E-mail address: ajzasl@technion.ac.il.
    Received: August 10, 2022; Accepted: September 23, 2022.

