## Communications in Optimization Theory

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# SMOOTH STABLE INVARIANT MANIFOLDS ON TIME SCALES 

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#### Abstract

This paper focuses on the problems of invariant manifolds for nonuniformly hyperbolic systems on time scales. We establish the existence of smooth stable invariant manifolds for a nonlinear dynamical system on time scales in Banach spaces assuming that the corresponding linearized system admits a nonuniform exponential dichotomy.


Keywords. Time scales; Nonuniform exponential dichotomies; Stable invariant manifold; Nonuniformly hyperbolic system.

2010 Mathematics Subject Classification. 34C45.

## 1. Introduction

Dynamical systems or dynamic equations on time scales originate from [1, 2] and allow a simultaneous treatment of continuous dynamical systems, discrete dynamical systems and dynamical systems on the general time scales. The concept of uniform or nonuniform exponential dichotomies on time scales introduced in $[3,4,5,6]$ is a very important method and tool to explore the dynamic behavior of nonautonomous dynamical systems such as the existence and roughness [4, 5, 7], the Hartman-Grobman theorems [6, 8, 9], periodic solutions [4, 11], (pseudo) almost-periodic solutions [10, 12, 13, 14, 15, 16] and impulsive dynamic systems [17].

[^0]As one of the most important and useful properties, the classical theory of invariant manifolds provides a geometric structure to describe and understand the qualitative behavior of nonlinear dynamical systems and has been widely recognized both in mathematics and in applications [18]. In particular, with the help of nonuniform exponential dichotomies, Zhang, Fan and Chang [6] investigated the existence of Lipschitz stable invariant manifolds for nonuniformly hyperbolic systems on measure chains. However, there are few results to consider smooth stable invariant manifolds on time scales, which is quite different from the existing results and is much more challenging.

The content of this paper is as follows. In Section 2, we introduce some basic preliminary results on time scales in order to make this paper self-contained. Section 3 focuses on establishing smooth stable invariant manifolds for nonuniformly hyperbolic systems on time scales with the help of nonuniform exponential dichotomies.

## 2. Preliminaries

We first introduce some basic terminologies and results of the calculus on time scales. We refer the readers to [1, 2] for more details.

Let $(X,\|\cdot\|)$ be a Banach space. A time scale $\mathbb{T}$ is defined as a nonempty closed subset of the real numbers. Define the forward jump operator $\sigma: \mathbb{T} \rightarrow \mathbb{T}$ and the graininess function $\mu(t)=\sigma(t)-t$ for any $t \in \mathbb{T}$. We assume that $\mathbb{T}$ is unbounded below and above. Let $\mathbb{T}_{\tau}^{+}:=\{t \in$ $\mathbb{T}: \tau \leq t\}$ and $\mathbb{T}_{\tau}^{-}:=\{t \in \mathbb{T}: t \leq \tau\}$ for any $\tau \in \mathbb{T} . \mathrm{C}_{\mathrm{rd}}(\mathbb{T}, X)$ denotes the set of rd-continuous functions $g: \mathbb{T} \rightarrow X . \mathscr{R}^{+}(\mathbb{T}, \mathbb{R}):=\left\{g \in \mathrm{C}_{\mathrm{rd}}(\mathbb{T}, \mathbb{R}): 1+\mu(t) g(t)>0\right.$, for $\left.t \in \mathbb{T}\right\}$ is the space of positively regressive functions. Define $(\varphi \oplus \psi)(t):=\varphi(t)+\psi(t)+\mu(t) \varphi(t) \psi(t), \ominus \varphi:=$ $-\frac{\varphi(t)}{1+\mu(t) \varphi(t)},(\omega \odot \varphi)(t):=\lim _{h \searrow \mu(t)} \frac{(1+h \varphi(t))^{\omega}-1}{h}$ for a given $\omega \in \mathbb{R}^{+}$and for any $t \in$ $\mathbb{T}, \varphi, \psi \in \mathscr{R}^{+}(\mathbb{T}, \mathbb{R})$. If $\varphi \in \mathscr{R}^{+}(\mathbb{T}, \mathbb{R})$, then we define the exponential function by

$$
e_{\varphi}(t, s)=\exp \left\{\int_{s}^{t} \zeta_{\mu(\tau)}(\varphi(\tau)) \Delta \tau\right\} \text { with } \zeta_{h}(z)= \begin{cases}z & \text { if } \quad h=0 \\ \log (1+h z) / h & \text { if } \quad h \neq 0\end{cases}
$$

for $s, t \in \mathbb{T}$, where $\log$ is the principal logarithm. Let $\kappa=\min \{t \in \mathbb{T}, 0 \leq t\}$. For any $\varphi \in$ $\mathrm{C}_{\mathrm{rd}}\left(\mathbb{T}_{\kappa}^{+}, \mathbb{R}\right)$, we introduce the abbreviation $[\varphi]^{*}:=\sup _{t \in \mathbb{T}_{\kappa}^{+}}(\varphi(t)),[\varphi]_{*}:=\inf _{t \in \mathbb{T}_{\kappa}^{+}}(\varphi(t))$ and the
notations $0 \triangleleft \varphi \Leftrightarrow 0<[\varphi]_{*}$. It is clear to see that

$$
\lim _{t \rightarrow \infty} e_{\ominus \varphi}(t, \tau)=0, \lim _{\tau \rightarrow-\infty} e_{\ominus \varphi}(t, \tau)=0, e_{\varphi}(t, \kappa) \geq 1 \text { for } \kappa \leq t
$$

for $0<[\varphi]_{*}$.
Let $\mathscr{B}(X)$ be the space of bounded linear operators defined on $X$. We consider the following systems

$$
\begin{gather*}
x^{\Delta}=A(t) x,  \tag{2.1}\\
x^{\Delta}=A(t) x+f(t, x), \tag{2.2}
\end{gather*}
$$

where $A(t) \in \mathrm{C}_{\mathrm{rd}}\left(\mathbb{T}_{\kappa}^{+}, \mathscr{B}(X)\right), f: \mathbb{T}_{\kappa}^{+} \times X \rightarrow X$. Let $T(t, s)$ be the evolution operator satisfying $T(t, s) x(s)=x(t)$ for $s \leq t, t, s \in \mathbb{T}$ and any solution $x(t)$ of equation (2.1).

Definition 2.1 ([6]). (2.1) is said to have a nonuniform exponential dichotomy on a time scale $\mathbb{T}$ if there are a projection $P(t): X \rightarrow X$ for $\kappa \leq t$, a constant $K>1$ and growth rates $0 \triangleleft a, 0 \triangleleft$ $b, 0 \unlhd \rho$ such that, for any $\kappa \leq s \leq t, P(t) T(t, s)=T(t, s) P(s), T_{Q}(t, s):=T(t, s) \mid Q(s) X: Q(s) X \rightarrow$ $Q(t) X$ is invertible, where $Q(t)=\mathrm{id}-P(t)$, and

$$
\begin{align*}
\|T(t, s) P(s)\| & \leq K e_{\ominus a}(t, s) e_{\rho}(s, \kappa) \\
\left\|T_{Q}(t, s)^{-1} Q(t)\right\| & \leq K e_{\ominus b}(t, s) e_{\rho}(t, \kappa) \tag{2.3}
\end{align*}
$$

We then define the stable and unstable subspaces for each $\kappa \leq t$ by

$$
E(t)=P(t)(X) \quad \text { and } \quad F(t)=Q(t)(X)
$$

We denote by $\partial$ the partial derivative with respect to the second variable of any given function of two variables and assume that:
(1) $f(t, 0)=0$ for any $\kappa \leq t$;
(2) there exists $c>0$ such that

$$
\begin{equation*}
\left\|\frac{\partial f}{\partial x}(t, x)\right\| \leq c e_{\ominus(3 \odot \rho)}(t, \kappa) \tag{2.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\frac{\partial f}{\partial x}\left(t, x_{1}\right)-\frac{\partial f}{\partial x}\left(t, x_{2}\right)\right\| \leq c e_{\ominus(3 \odot \rho)}(t, \kappa)\left\|x_{1}-x_{2}\right\| \tag{2.5}
\end{equation*}
$$

for any $\kappa \leq t, x_{1}, x_{2} \in X$.
We also denote by $\mathscr{X}$ the space of rd-continuous functions $\Phi: \mathbb{T}_{\kappa}^{+} \times E(s) \rightarrow X$ of class $C^{1}$ in $\xi \in E(s)$ such that for each $\kappa \leq s$ :
(1) $\Phi(s, E(s)) \subset F(s)$ and $\Phi(s, 0)=0$;
(2)

$$
\begin{align*}
\|(\partial \Phi / \partial \xi)(s, \xi)\| & \leq 1  \tag{2.6}\\
\left\|(\partial \Phi / \partial \xi)\left(s, \xi_{1}\right)-(\partial \Phi / \partial \xi)\left(s, \xi_{2}\right)\right\| & \leq\left\|\xi_{1}-\xi_{2}\right\|
\end{align*}
$$

for every $\xi_{1}, \xi_{2} \in E(s)$.
It is easy to show that $\mathscr{X}$ is a Banach space with the norm

$$
|\Phi|^{\prime}=\sup \{\|\Phi(s, \xi)\| /\|\xi\|: \kappa \leq s \text { and } \xi \in E(s) \backslash\{0\}\} .
$$

Given $\Phi \in \mathscr{X}$, we consider the graph

$$
\begin{equation*}
\mathscr{W}=\left\{(s, \xi, \Phi(s, \xi)):(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)\right\} \tag{2.7}
\end{equation*}
$$

Moreover, for each $(s, u(s), v(s)) \in \mathbb{T}_{\kappa}^{+} \times E(s) \times F(s)$ we consider

$$
\begin{equation*}
\Psi_{\gamma}(s, u(s), v(s))=(t, u(t), v(t)), \quad t-s=\gamma \geq 0 \tag{2.8}
\end{equation*}
$$

generated by equation (2.2), where

$$
\begin{align*}
& u(t)=U(t, s) u(s)+\int_{s}^{t} U(t, \sigma(\tau)) f(\tau, u(\tau), v(\tau)) \Delta \tau  \tag{2.9}\\
& v(t)=V(t, s) v(s)+\int_{s}^{t} V(t, \sigma(\tau)) f(\tau, u(\tau), v(\tau)) \Delta \tau \tag{2.10}
\end{align*}
$$

where $U(t, s)=T(t, s) P(s)$ and $V(t, s)=T_{Q}(t, s) Q(s)$.

## 3. EXistence of smooth stable manifolds

In this section, we establish the existence of smooth stable invariant manifolds for nonuniformly hyperbolic systems on time scales. Let $\mathscr{X}^{*}$ be the space of rd-continuous functions $z: \mathbb{T}_{\kappa}^{+} \times E(s) \rightarrow X$ of class $C^{1}$ in $\xi \in E(s)$ such that for $\kappa \leq s:$
(1) $z(t, \xi) \in E(t), z(t, 0)=0$ for every $s \leq t$ and $z(s, \xi)=\xi$;
(2)

$$
\begin{equation*}
\|(\partial z / \partial \xi)(t, \xi)\| \leq 2 K e_{\ominus a}(t, s) e_{\rho}(s, \kappa) \tag{3.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|(\partial z / \partial \xi)\left(t, \xi_{1}\right)-(\partial z / \partial \xi)\left(t, \xi_{2}\right)\right\| \leq 2 K e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\| \tag{3.2}
\end{equation*}
$$

for every $s \leq t$ and $\xi_{1}, \xi_{2} \in E(s)$.
It is not difficult to show that $\mathscr{X}^{*}$ is a Banach space with the norm

$$
\begin{equation*}
\|z\|^{*}=\sup \left\{\frac{\|z(t, \xi)\|}{\|\xi\| e_{\ominus a}(t, s) e_{\rho}(s, \kappa)}: s \leq t, \xi \in E(s) \backslash\{0\}\right\} \tag{3.3}
\end{equation*}
$$

and $\|z\|^{*} \leq K$ for each $z \in \mathscr{X}^{*}$.
The following is our main result. It establishes the existence of a smooth stable invariant manifold for equation (2.2).

Theorem 3.1. Assume that equation (2.1) admits a nonuniform exponential dichotomy and $[a \mu]^{*}<\infty,[\rho \mu]^{*}<\infty$. If $[a \oplus b \ominus \rho]_{*}>0$ and $c$ is sufficiently small, then there exists a unique function $\Phi \in \mathscr{X}$ such that the set $\mathscr{W}$ is forward invariant under $\Psi_{\gamma}$, in the sense that

$$
\begin{equation*}
\Psi_{\gamma}(s, \xi, \Phi(s, \xi)) \in \mathscr{W} \quad \text { for every } \quad(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s), \gamma \geq 0 \tag{3.4}
\end{equation*}
$$

Furthermore, the graph $\mathscr{W}$ is of class $C^{1}$ for $\xi \in E(s)$, and there exist constants $d_{1}, d_{2}>0$ such that

$$
\begin{equation*}
\left\|\Psi_{\gamma}\left(s, \xi_{1}, \Phi\left(s, \xi_{1}\right)\right)-\Psi_{\gamma}\left(s, \xi_{2}, \Phi\left(s, \xi_{2}\right)\right)\right\| \leq d_{1} e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\| \tag{3.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\frac{\partial \Psi_{\gamma}}{\partial \xi}\left(s, \xi_{1}, \Phi\left(s, \xi_{1}\right)\right)-\frac{\partial \Psi_{\gamma}}{\partial \xi}\left(s, \xi_{2}, \Phi\left(s, \xi_{2}\right)\right)\right\| \leq d_{2} e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\| \tag{3.6}
\end{equation*}
$$

for $t-s=\gamma \geq 0$ and $\left(s, \xi_{1}\right),\left(s, \xi_{2}\right) \in \mathbb{T}_{\kappa}^{+} \times E(s)$.

The proof of Theorem 3.1 will be obtained in several steps.

Lemma 3.1. For $s \leq t$, we have
(3.11) $\left\|(\partial \Phi / \partial \xi)\left(t, z\left(t, \xi_{1}\right)\right)-(\partial \Phi / \partial \xi)\left(t, z\left(t, \xi_{2}\right)\right)\right\| \leq 6 K^{2} e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|$,

$$
\begin{gather*}
\left\|(\partial f / \partial \xi)\left(t, z\left(t, \xi_{1}\right), \Phi\left(t, z\left(t, \xi_{1}\right)\right)\right)-(\partial f / \partial \xi)\left(t, z\left(t, \xi_{2}\right), \Phi\left(t, z\left(t, \xi_{2}\right)\right)\right)\right\|  \tag{3.12}\\
\leq 24 K^{2} c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{gather*}
$$

for every $\Phi \in \mathscr{X}, z \in \mathscr{X}^{*}, \xi_{1}, \xi_{2} \in E(s)$.

Proof. It follows from (3.1) that

$$
\begin{aligned}
\left\|z\left(t, \xi_{1}\right)-z\left(t, \xi_{2}\right)\right\| & \leq \sup _{\theta \in[0,1]}\left\|\frac{\partial z}{\partial \xi}\left(t, \xi_{1}+\theta\left(\xi_{2}-\xi_{1}\right)\right)\right\| \cdot\left\|\xi_{1}-\xi_{2}\right\| \\
& \leq 2 \operatorname{Ke}_{\ominus a}(t, s) e_{\rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\| .
\end{aligned}
$$

By (2.6) and (3.1), we have

$$
\left\|\frac{\partial \Phi}{\partial \xi}(t, z(t, \xi))\right\| \leq\left\|\frac{\partial \Phi}{\partial z}(t, z)\right\| \cdot\left\|\frac{\partial z}{\partial \xi}(t, \xi)\right\| \leq 2 K e_{\ominus a}(t, s) e_{\rho}(s, \kappa)
$$

By (2.4), (3.1) and (3.8), we have

$$
\begin{aligned}
\left\|\frac{\partial f}{\partial \xi}(t, z(t, \xi), \Phi(t, z(t, \xi)))\right\| \leq & \left\|\frac{\partial f}{\partial z}(t, z, \Phi)\right\| \cdot\left\|\frac{\partial z}{\partial \xi}(t, \xi)\right\| \\
& +\left\|\frac{\partial f}{\partial \Phi}(t, z, \Phi)\right\| \cdot\left\|\frac{\partial \Phi}{\partial \xi}(t, z)\right\| \\
& \leq 4 K c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{\rho}(s, \kappa)
\end{aligned}
$$

Writing $z^{i}=z\left(t, \xi_{i}\right), i=1,2$. It follows from (2.6) and (3.7) that

$$
\begin{aligned}
& \left\|\Phi\left(t, z\left(t, \xi_{1}\right)\right)-\Phi\left(t, z\left(t, \xi_{2}\right)\right)\right\| \\
& \leq \sup _{\theta \in[0,1]}\left\|\frac{\partial \Phi}{\partial z}\left(t, z^{1}+\theta\left(z^{2}-z^{1}\right)\right)\right\| \cdot\left\|z\left(t, \xi_{1}\right)-z\left(t, \xi_{2}\right)\right\| \\
& \leq 2 K e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\| .
\end{aligned}
$$

By (2.6), (3.1), (3.2) and (3.7), we have

$$
\begin{aligned}
A_{1}(t): & =\left\|\frac{\partial \Phi}{\partial z}\left(t, z^{1}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{1}\right)-\frac{\partial \Phi}{\partial z}\left(t, z^{1}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{2}\right)\right\| \\
& \leq 2 K e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

and

$$
\begin{aligned}
A_{2}(t): & =\left\|\frac{\partial \Phi}{\partial z}\left(t, z^{1}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{2}\right)-\frac{\partial \Phi}{\partial z}\left(t, z^{2}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{2}\right)\right\| \\
& \leq 2 K e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\left\|z^{1}-z^{2}\right\| \\
& \leq 4 K^{2} e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\| .
\end{aligned}
$$

Therefore, one has

$$
\begin{aligned}
& \left\|\frac{\partial \Phi}{\partial \xi}\left(t, z\left(t, \xi_{1}\right)\right)-\frac{\partial \Phi}{\partial \xi}\left(t, z\left(t, \xi_{2}\right)\right)\right\| \\
& =\left\|\frac{\partial \Phi}{\partial z}\left(t, z^{1}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{1}\right)-\frac{\partial \Phi}{\partial z}\left(t, z^{2}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{2}\right)\right\| \\
& \leq A_{1}(t)+A_{2}(t) \leq 6 K^{2} e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

since $K>1$. Writing $\Phi^{i}=\Phi\left(t, z\left(t, \xi_{i}\right)\right), i=1,2$. By (2.4), (2.5), (3.1), (3.2), (3.7) and (3.10) we have

$$
\begin{aligned}
B_{1}(t): & =\left\|\frac{\partial f}{\partial z}\left(t, z^{1}, \Phi^{1}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{1}\right)-\frac{\partial f}{\partial z}\left(t, z^{1}, \Phi^{1}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{2}\right)\right\| \\
& \leq 2 K c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

and

$$
\begin{aligned}
B_{2}(t): & =\left\|\frac{\partial f}{\partial z}\left(t, z^{1}, \Phi^{1}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{2}\right)-\frac{\partial f}{\partial z}\left(t, z^{2}, \Phi^{2}\right) \frac{\partial z}{\partial \xi}\left(t, \xi_{2}\right)\right\| \\
& \leq 2 K c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\left(\left\|z^{1}-z^{2}\right\|+\left\|\Phi^{1}-\Phi^{2}\right\|\right) \\
& \leq 8 K^{2} c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

On the other hand, it follows from (3.8) and (3.11) that

$$
\begin{aligned}
B_{3}(t): & =\left\|\frac{\partial f}{\partial \Phi}\left(t, z^{1}, \Phi^{1}\right) \frac{\partial \Phi}{\partial \xi}\left(t, z^{1}\right)-\frac{\partial f}{\partial \Phi}\left(t, z^{1}, \Phi^{1}\right) \frac{\partial \Phi}{\partial \xi}\left(t, z^{2}\right)\right\| \\
& \leq 6 K^{2} c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

and

$$
\begin{aligned}
B_{4}(t): & =\left\|\frac{\partial f}{\partial \Phi}\left(t, z^{1}, \Phi^{1}\right) \frac{\partial \Phi}{\partial \xi}\left(t, z^{2}\right)-\frac{\partial f}{\partial \Phi}\left(t, z^{2}, \Phi^{2}\right) \frac{\partial \Phi}{\partial \xi}\left(t, z^{2}\right)\right\| \\
& \leq 2 K c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\left(\left\|z^{1}-z^{2}\right\|+\left\|\Phi^{1}-\Phi^{2}\right\|\right) \\
& \leq 8 K^{2} c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

Therefore, we have

$$
\begin{aligned}
& \left\|\frac{\partial f}{\partial \xi}\left(t, z\left(t, \xi_{1}\right), \Phi\left(t, z\left(t, \xi_{1}\right)\right)\right)-\frac{\partial f}{\partial \xi}\left(t, z\left(t, \xi_{2}\right), \Phi\left(t, z\left(t, \xi_{2}\right)\right)\right)\right\| \\
\leq & B_{1}(t)+B_{2}(t)+B_{3}(t)+B_{4}(t) \\
\leq & 24 K^{2} c e_{\ominus(3 \odot \rho)}(t, \kappa) e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

Lemma 3.2. Given $c>0$ sufficiently small and $(s, \xi, \Phi) \in \mathbb{T}_{\kappa}^{+} \times E(s) \times \mathscr{X}$, there exists a unique function $z \in \mathscr{X}^{*}$ such that (2.9) holds for every $s \leq t$.

Proof. Given $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$ and $\Phi \in \mathscr{X}$, we define an operator $L$ in $\mathscr{X}^{*}$ by

$$
(L z)(t, \xi)=U(t, s) \xi+\int_{s}^{t} U(t, \sigma(\tau)) f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau
$$

Obviously, $(L z)(t, \xi) \in E(t),(L z)(t, 0)=0$ and $(L z)(s, \xi)=\xi$. It follows from (2.4), (2.6) and (3.3) that

$$
\begin{align*}
\|f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi)))\| & \leq c e_{\ominus(3 \odot \rho)}(\tau, \kappa)\|(z(\tau, \xi), \Phi(\tau, z(\tau, \xi)))\| \\
& \leq 2 c e_{\ominus(3 \odot \rho)}(\tau, \kappa)\|z(\tau, \xi)\|  \tag{3.13}\\
& \leq 4 K c e_{\ominus(3 \odot \rho)}(\tau, \kappa) e_{\ominus a}(\tau, s) e_{\rho}(s, \kappa)\|\xi\|
\end{align*}
$$

By (2.3), we have

$$
\begin{aligned}
& \int_{s}^{t}\|U(t, \sigma(\tau))\|\|f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi)))\| \\
& \leq 4 K^{2} c\|\xi\| \int_{s}^{t} e_{\ominus a}(t, \sigma(\tau)) e_{\rho}(\sigma(\tau), \kappa) e_{\ominus(3 \odot \rho)}(\tau, \kappa) e_{\ominus a}(\tau, s) e_{\rho}(s, \kappa) \Delta \tau \\
& \leq 4 K^{2} c e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\|\xi\| \int_{s}^{t}(1+a \mu(\tau))(1+\rho \mu(\tau)) e_{\ominus(2 \odot \rho)}(\tau, \kappa) \Delta \tau \\
& \leq 4 K^{2} c \lambda^{\prime} e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\|\xi\|
\end{aligned}
$$

where

$$
\lambda^{\prime}=\frac{\left(1+[a \mu]^{*}\right)\left(1+[\rho \mu]^{*}\right)\left(1+[(2 \odot \rho) \mu]^{*}\right)}{[2 \odot \rho]_{*}}
$$

Then

$$
\begin{aligned}
\|(L z)(t, \xi)\| & \leq\|U(t, s) \xi\|+\int_{s}^{t}\|U(t, \sigma(\tau))\|\|f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi)))\| \Delta \tau \\
& \leq K e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\|\xi\|+4 K^{2} c \lambda^{\prime} e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\|\xi\|
\end{aligned}
$$

This implies that $\|L z\|^{*} \leq K+4 K^{2} c \lambda^{\prime}<\infty$. By (2.3) and (3.9), one has

$$
\begin{aligned}
& \left\|\frac{\partial(L z)}{\partial \xi}(t, \xi)\right\| \leq K e_{\ominus a}(t, s) e_{\rho}(s, \kappa) \\
& \quad+4 K^{2} c \int_{s}^{t} e_{\ominus a}(t, \sigma(\tau)) e_{\rho}(\sigma(\tau), \kappa) e_{\ominus(3 \odot \rho)}(\tau, \kappa) e_{\ominus a}(\tau, s) e_{\rho}(s, \kappa) \Delta \tau \\
& \leq K e_{\ominus a}(t, s) e_{\rho}(s, \kappa)+4 K^{2} c \lambda^{\prime} e_{\ominus a}(t, s) e_{\rho}(s, \kappa) \leq 2 K e_{\ominus a}(t, s) e_{\rho}(s, \kappa)
\end{aligned}
$$

since $c$ is sufficiently small so that $4 K^{2} c \lambda^{\prime} \leq K$. For any $\xi_{1}, \xi_{2} \in E(s)$, we have

$$
\begin{aligned}
& \left\|\frac{\partial(L z)}{\partial \xi}\left(t, \xi_{1}\right)-\frac{\partial(L z)}{\partial \xi}\left(t, \xi_{2}\right)\right\| \leq 24 K^{2} c\left\|\xi_{1}-\xi_{2}\right\| \\
& \quad \times \int_{s}^{t} e_{\ominus a}(t, \sigma(\tau)) e_{\rho}(\sigma(\tau), s) e_{\ominus(3 \odot \rho)}(\tau, \kappa) e_{\ominus a}(\tau, s) e_{(2 \odot \rho)}(s, \kappa) \Delta \tau \\
& \leq \\
& 24 K^{2} c \lambda^{\prime} e_{\ominus a}(t, s) e_{(2 \odot \rho)}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\| \leq 2 K e_{\ominus a}(t, s) e_{(2 \odot \rho)}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

since $c$ is sufficiently small. Therefore, $L\left(\mathscr{X}^{*}\right) \subset \mathscr{X}^{*}$. On the other hand, for each $z_{1}, z_{2} \in \mathscr{X}^{*}$, we conclude that

$$
\begin{aligned}
& \left\|f\left(\tau, z_{1}(\tau, \xi), \Phi\left(\tau, z_{1}(\tau, \xi)\right)\right)-f\left(\tau, z_{2}(\tau, \xi), \Phi\left(\tau, z_{2}(\tau, \xi)\right)\right)\right\| \\
& \leq c e_{\ominus(3 \odot \rho)}(\tau, \kappa)\left\|\left(z_{1}(\tau, \xi), \Phi\left(\tau, z_{1}(\tau, \xi)\right)\right)-\left(z_{2}(\tau, \xi), \Phi\left(\tau, z_{2}(\tau, \xi)\right)\right)\right\| \\
& \leq 2 c e_{\ominus(3 \odot \rho)}(\tau, \kappa)\left\|z_{1}(\tau, \xi)-z_{2}(\tau, \xi)\right\| \\
& \leq 2 c e_{\ominus(3 \odot \rho)}(\tau, \kappa) e_{\ominus a}(\tau, s) e_{\rho}(s, \kappa)\|\xi\|\left\|z_{1}-z_{2}\right\|^{*} .
\end{aligned}
$$

It follows from (2.3) that

$$
\begin{aligned}
& \|\left(L z_{1}\right)(t)-\left(L z_{2}\right)(t)\|\leq 2 K c\| \xi\| \| z_{1}-z_{2} \|^{*} \\
& \quad \times \int_{s}^{t} e_{\ominus a}(t, \sigma(\tau)) e_{\rho}(\sigma(\tau), \kappa) e_{\ominus(3 \odot \rho)}(\tau, \kappa) e_{\ominus a}(\tau, s) e_{\rho}(s, \kappa) \Delta \tau \\
& \leq 2 K c \lambda^{\prime} e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\|\xi\|\left\|z_{1}-z_{2}\right\|^{*}
\end{aligned}
$$

This implies that $\left\|L z_{1}-L z_{2}\right\|^{*} \leq 2 K c \lambda^{\prime}\left\|z_{1}-z_{2}\right\|^{*}$ and $L$ is a contraction if $c$ is sufficiently small. Therefore, there exists a unique function $z \in \mathscr{X}^{*}$ such that $L z=z$.

Let $z=z^{\Phi}(t, \xi)$ be the unique function given by Lemma 3.2, that is,

$$
\begin{equation*}
z(t, \xi)=U(t, s) \xi+\int_{s}^{t} U(t, \sigma(\tau)) f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau \tag{3.14}
\end{equation*}
$$

for each $s \leq t$.

Lemma 3.3. Let $\Phi \in \mathscr{X}$ and $z$ be the unique function given by Lemma 3.2. Then the following properties hold:
(1) if

$$
\begin{equation*}
\Phi(t, z(t, \xi))=V(t, s) \Phi(s, \xi)+\int_{s}^{t} V(t, \sigma(\tau)) f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau \tag{3.15}
\end{equation*}
$$

for every $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$ and $s \leq t$, then

$$
\begin{equation*}
\Phi(s, \xi)=-\int_{s}^{\infty} V(\sigma(\tau), s)^{-1} f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau \tag{3.16}
\end{equation*}
$$

(2) if identity (3.16) holds for every $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$, then (3.15) holds for every $(s, \xi) \in$ $\mathbb{T}_{\kappa}^{+} \times E(s)$.

Proof. It follows from (2.3) and (3.13) that

$$
\begin{aligned}
& \int_{s}^{\infty}\left\|V(\sigma(\tau), s)^{-1}\right\|\|f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi)))\| \Delta \tau \\
& \leq 4 K^{2} c\|\xi\| \int_{s}^{t} e_{\ominus b}(\sigma(\tau), s) e_{\rho}(\sigma(\tau), \kappa) e_{\ominus(3 \odot \rho)}(\tau, \kappa) e_{\ominus a}(\tau, s) e_{\rho}(s, \kappa) \Delta \tau \\
& \leq 4 K^{2} c\|\xi\| e_{a \oplus b \oplus \rho}(s, \kappa) \int_{s}^{t} \frac{1+\rho \mu(\tau)}{1+b \mu(\tau)} e_{\ominus(a \oplus b \oplus(2 \odot \rho))}(\tau, \kappa) \Delta \tau \\
& \leq 4 K^{2} c\|\xi\|\left(\frac{1+[\rho \mu]^{*}}{1+[b \mu]_{*}}\right)\left(\frac{1}{[a \oplus b \oplus(2 \odot \rho)]_{*}}+[\mu]^{*}\right)<\infty .
\end{aligned}
$$

This implies that (3.16) is well-defined. If (3.15) holds for every $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$ and $s \leq t$, then identity (3.15) can be written in the form

$$
\begin{equation*}
\Phi(s, \xi)=V(t, s)^{-1} \Phi(t, z(t, \xi))-\int_{s}^{t} V(\sigma(\tau), s)^{-1} f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau \tag{3.17}
\end{equation*}
$$

By (2.3), (2.6), and (3.1), we have

$$
\begin{aligned}
\left\|V(t, s)^{-1} \Phi(t, z(t, \xi))\right\| & \leq K e_{\ominus b}(t, s) e_{\rho}(t, \kappa)\|z(t, \xi)\| \\
& \leq 2 K^{2}\|\xi\| e_{\ominus b}(t, s) e_{\rho}(t, \kappa) e_{\ominus a}(t, s) e_{\rho}(s, \kappa) \\
& \leq 2 K^{2}\|\xi\| e_{\ominus(a \oplus b \ominus \rho)}(t, \kappa) e_{a \oplus b \oplus \rho}(s, \kappa) .
\end{aligned}
$$

Therefore, (3.16) holds when letting $t \rightarrow \infty$ since $[a \oplus b \ominus \rho]_{*}>0$.
We now assume that (3.16) holds for every $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$. It follows from (3.16) that

$$
\begin{aligned}
V(t, s) \Phi(s, \xi)= & -\int_{s}^{\infty} V(t, \sigma(\tau)) f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau \\
= & -\int_{s}^{t} V(t, \sigma(\tau)) f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau \\
& -\int_{t}^{\infty} V(t, \sigma(\tau)) f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau \\
= & -\int_{s}^{t} V(t, \sigma(\tau)) f(\tau, z(\tau, \xi), \Phi(\tau, z(\tau, \xi))) \Delta \tau+\Phi(t, z(t, \xi))
\end{aligned}
$$

This completes the proof of the lemma.

Lemma 3.4. If $c$ is sufficiently small, then there exists $K_{1}>0$ such that

$$
\begin{equation*}
\left\|z^{\Phi_{1}}(t, \xi)-z^{\Phi_{2}}(t, \xi)\right\| \leq K_{1} e_{\gamma \ominus a}(t, s) e_{\rho}(s, \kappa)\|\xi\| \cdot\left|\Phi_{1}-\Phi_{2}\right|^{\prime} \tag{3.18}
\end{equation*}
$$

for every $\Phi_{1}, \Phi_{2} \in \mathscr{X},(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$ and $s \leq t$.

Proof. Write $z_{i}=z^{\Phi_{i}}$ for $i=1,2$. We first note that

$$
\begin{aligned}
& \left\|\Phi_{1}\left(\tau, z_{1}(\tau, \xi)\right)-\Phi_{2}\left(\tau, z_{2}(\tau, \xi)\right)\right\| \\
& \leq\left\|\Phi_{1}\left(\tau, z_{1}(\tau, \xi)\right)-\Phi_{2}\left(\tau, z_{1}(\tau, \xi)\right)\right\|+\left\|\Phi_{2}\left(\tau, z_{1}(\tau, \xi)\right)-\Phi_{2}\left(\tau, z_{2}(\tau, \xi)\right)\right\| \\
& \leq\left\|z_{1}(\tau, \xi)\right\| \cdot\left|\Phi_{1}-\Phi_{2}\right|^{\prime}+\left\|z_{1}(\tau, \xi)-z_{2}(\tau, \xi)\right\|
\end{aligned}
$$

Then we have

$$
\begin{align*}
& \left\|f\left(\tau, z_{1}(\tau, \xi), \Phi_{1}\left(\tau, z_{1}(\tau, \xi)\right)\right)-f\left(\tau, z_{1}(\tau, \xi), \Phi_{2}\left(\tau, z_{2}(\tau, \xi)\right)\right)\right\| \\
& \leq c e_{\ominus(3 \odot \rho)}(\tau, \kappa)\left(\left\|z_{1}(\tau, \xi)\right\| \cdot\left|\Phi_{1}-\Phi_{2}\right|^{\prime}+2\left\|z_{1}(\tau, \xi)-z_{2}(\tau, \xi)\right\|\right)  \tag{3.19}\\
& \leq 2 K c e_{\ominus(3 \odot \rho)}(\tau, \kappa) e_{\ominus a}(\tau, s) e_{\rho}(s, \kappa)\|\xi\| \cdot\left|\Phi_{1}-\Phi_{2}\right|^{\prime} \\
& \quad+2 c e_{\ominus(3 \odot \rho)}(\tau, \kappa)\left\|z_{1}(\tau, \xi)-z_{2}(\tau, \xi)\right\| .
\end{align*}
$$

It follows from (2.3) that

$$
\begin{aligned}
e_{\ominus a}(s, t)\left\|z_{1}(t, \xi)-z_{2}(t, \xi)\right\| \leq & 2 K^{2} c \lambda^{\prime} e_{\rho}(s, \kappa)\|\xi\| \cdot\left|\Phi_{1}-\Phi_{2}\right|^{\prime} \\
& +\gamma \int_{s}^{t} e_{\ominus a}(s, \tau)\left\|z_{1}(\tau, \xi)-z_{2}(\tau, \xi)\right\| \Delta \tau
\end{aligned}
$$

where

$$
\gamma=2 K c\left(1+[a \mu]^{*}\right)\left(1+[\rho \mu]^{*}\right) .
$$

By using Gronwall's inequality (see Section 6 in [2]), we have

$$
\left\|z_{1}(t, \xi)-z_{2}(t, \xi)\right\| \leq 2 K^{2} c \lambda^{\prime} e_{\gamma \ominus a}(t, s) e_{\rho}(s, \kappa)\|\xi\| \cdot\left|\Phi_{1}-\Phi_{2}\right|^{\prime} .
$$

Lemma 3.5. If c is sufficiently small, then there exists a unique function $\Phi \in \mathscr{X}$ such that (3.16) holds for every $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$.

Proof. For each $\Phi \in \mathscr{X}$ and $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$, we define an operator $J$ by

$$
(J \Phi)(s, \xi)=-\int_{s}^{\infty} V(\sigma(\tau), s)^{-1} f\left(\tau, z^{\Phi}(\tau, \xi), \Phi\left(\tau, z^{\Phi}(\tau, \xi)\right)\right) \Delta \tau
$$

where $z^{\Phi}$ is the unique function given by Lemma 3.2. It is easy to show that $J \Phi$ is of class $C^{1}$ in $\xi \in E(s), J \Phi(s, E(s)) \subset F(s)$ and $J \Phi(s, 0)=0$. By (2.3) and (3.9), we have

$$
\begin{aligned}
\left\|\frac{\partial(J \Phi)}{\partial \xi}(s, \xi)\right\| & \leq \int_{s}^{\infty}\left\|V(\sigma(\tau), s)^{-1}\right\|\left\|\frac{\partial f}{\partial \xi}\right\| \Delta \tau \\
& \leq 4 K^{2} c\left(\frac{1+[\rho \mu]^{*}}{1+[b \mu]_{*}}\right)\left(\frac{1}{[a \oplus b \oplus(2 \odot \rho)]_{*}}+[\mu]^{*}\right)
\end{aligned}
$$

which implies that $\|(\partial(J \Phi) / \partial \xi)(s, \xi)\| \leq 1$ since $c$ is sufficiently small. It follows from (2.3) and (3.12) that

$$
\begin{aligned}
& \left\|\frac{\partial(J \Phi)}{\partial \xi}\left(s, \xi_{1}\right)-\frac{\partial(J \Phi)}{\partial \xi}\left(s, \xi_{2}\right)\right\| \\
& \leq \int_{s}^{\infty}\left\|V(\sigma(\tau), s)^{-1}\right\|\left\|\frac{\partial f}{\partial \xi}\left(\tau, \xi_{1}\right)-\frac{\partial f}{\partial \xi}\left(\tau, \xi_{2}\right)\right\| \\
& \leq 24 K^{3} c\left(\frac{1+[\rho \mu]^{*}}{1+[b \mu]_{*}}\right)\left(\frac{1}{[a \oplus b \oplus(2 \odot \rho)]_{*}}+[\mu]^{*}\right)\left\|\xi_{1}-\xi_{2}\right\| .
\end{aligned}
$$

Therefore, $J(\mathscr{X}) \subset \mathscr{X}$.
Now we show that $J$ is a contraction. Let $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$, for each $\Phi_{1}, \Phi_{2} \in \mathscr{X}$ and $z_{i}=z_{\xi}^{\Phi_{i}}$ for $i=1,2$. By (3.18) and (3.19), we have

$$
\begin{aligned}
C(\tau):= & \left\|f\left(\tau, z_{1}(\tau, \xi), \Phi_{1}\left(\tau, z_{1}(\tau, \xi)\right)\right)-f\left(\tau, z_{2}(\tau, \xi), \Phi_{2}\left(\tau, z_{2}(\tau, \xi)\right)\right)\right\| \\
\leq & 2\left(K+K_{1}\right) c e_{\ominus(3 \odot \rho)}(\tau, \kappa)\left(e_{\ominus a}(\tau, s)\right. \\
& \left.+e_{\gamma \ominus a}(\tau, s)\right) e_{\rho}(s, \kappa)\|\xi\| \cdot\left|\Phi_{1}-\Phi_{2}\right|^{\prime} .
\end{aligned}
$$

Then

$$
\begin{aligned}
& \left\|\left(J \Phi_{1}\right)(s, \xi)-\left(J \Phi_{2}\right)(s, \xi)\right\| \\
& \leq \int_{s}^{\infty}\left\|V(\sigma(\tau), s)^{-1}\right\| C(\tau) \Delta \tau \\
& \leq 2 K\left(K+K_{1}\right) c\left(\frac{1+[\rho \mu]^{*}}{1+[b \mu]_{*}}\right)\|\xi\| \cdot\left|\Phi_{1}-\Phi_{2}\right|^{\prime} \\
& \quad \times \int_{s}^{\infty} e_{\ominus b}(\tau, s) e_{\rho}(\tau, \kappa) e_{\ominus(3 \odot \rho)}(\tau, \kappa)\left(e_{\ominus a}(\tau, s)+e_{\gamma \ominus a}(\tau, s)\right) e_{\rho}(s, \kappa) \Delta \tau .
\end{aligned}
$$

If $c$ is sufficiently small, then

$$
\left\|\left(J \Phi_{1}\right)(s, \xi)-\left(J \Phi_{2}\right)(s, \xi)\right\| \leq \eta\|\xi\|\left|\Phi_{1}-\Phi_{2}\right|^{\prime}
$$

where

$$
\eta=2 K\left(K+K_{1}\right) c\left(\frac{1+[\rho \mu]^{*}}{1+[b \mu]_{*}}\right)\left(\frac{1}{[\gamma \ominus(a \oplus b \oplus(2 \odot \rho))]_{*}}+[\mu]^{*}\right)<1
$$

which means that $J$ is a contraction and has a unique fixed point $\Phi$ in $\mathscr{X}$.
We are now at the right position to establish Theorem 3.1.
Proof of Theorem 3.1. It follows from Lemma 3.2 that, for each $(s, \xi) \in \mathbb{T}_{\kappa}^{+} \times E(s)$ and $\Phi \in$ $\mathscr{X}$, there exists a unique function $z=z_{\xi}^{\Phi} \in \mathscr{X}^{*}$. By Lemmas 3.3 and 3.5 , for each $\kappa \leq s$ and $\xi \in E(s)$ there exists a unique function $\Phi$ such that (3.15) holds. Therefore, (3.4) holds and $\mathscr{W}$ is forward invariant under $\Psi_{\gamma}$. Meanwhile, since the function $\Phi$ is of class $C^{1}$ for $\xi \in E(s)$, the graph $\mathscr{W}$ is of class $C^{1}$ for $\xi \in E(s)$. For each $\left(s, \xi_{1}\right),\left(s, \xi_{2}\right) \in \mathbb{T}_{\kappa}^{+} \times E(s)$ and $\gamma=t-s \geq 0$, by (3.7) and (3.10) we have

$$
\begin{aligned}
& \left\|\Psi_{\gamma}\left(s, \xi_{1}, \Phi\left(s, \xi_{1}\right)\right)-\Psi_{\gamma}\left(s, \xi_{2}, \Phi\left(s, \xi_{2}\right)\right)\right\| \\
& =\left\|\left(t, z\left(t, \xi_{1}\right), \Phi\left(t, z\left(t, \xi_{1}\right)\right)\right)-\left(t, z\left(t, \xi_{2}\right), \Phi\left(t, z\left(t, \xi_{2}\right)\right)\right)\right\| \\
& \leq 4 K e_{\ominus a}(t, s) e_{\rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

and it follows from (3.2) and (3.12) that

$$
\begin{aligned}
& \left\|\frac{\partial \Psi_{\gamma}}{\partial \xi}\left(s, \xi_{1}, \Phi\left(s, \xi_{1}\right)\right)-\frac{\partial \Psi_{\gamma}}{\partial \xi}\left(s, \xi_{2}, \Phi\left(s, \xi_{2}\right)\right)\right\| \\
& \leq\left\|(\partial z)(\partial \xi)\left(t, \xi_{1}\right)-(\partial z)(\partial \xi)\left(t, \xi_{2}\right)\right\| \\
& \quad+\left\|(\partial \Phi)(\partial \xi)\left(t, z\left(t, \xi_{1}\right)\right)-(\partial \Phi)(\partial \xi)\left(t, z\left(t, \xi_{2}\right)\right)\right\| \\
& \leq \\
& \leq\left(2 K+6 K^{2}\right) e_{\ominus a}(t, s) e_{2 \odot \rho}(s, \kappa)\left\|\xi_{1}-\xi_{2}\right\|
\end{aligned}
$$

This completes the proof of the theorem.

## Acknowledgements

This research is supported by the Fund of Heilongjiang Education Committee (No. 12541127).

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    Received August 3, 2016; Accepted 6 December, 2016.

