



GLOBAL POSITIVE SOLUTIONS FOR A SYSTEM OF NONLINEAR FRACTIONAL DIFFERENTIAL EQUATIONS WITH VARIABLE DELAYS

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Abstract. In this paper, by employing some fixed point theorems, we establish the existence and uniqueness of the global positive solution for a system of nonlinear fractional differential equations with variable delays, involving the Caputo fractional derivative. Some examples are provided to illustrate our main results.

Keywords. Fixed point theorem; Global positive solution; Fractional differential system; Variable delay; Caputo fractional derivative.

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1. Introduction

Fractional differential equations theory has emerged as an interesting area to explore in recent years due to its applications in engineering and other related fields. A very interesting account of the study of fractional differential equations can be found in [2, 3, 4, 5, 6, 7]. Furthermore, fractional differential equations with delays have gained much attention of research; see [1, 8] and references cited therein.

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In [9], Ye, Ding and Gao have studied the existence of a positive solution for a delay fractional differential equation

$$\begin{cases} D^\alpha [x(t) - x(0)] = x(t) f(t, x_t), & t \in (0, T], \\ x(t) = \phi(t) \geq 0, & t \in [-r, 0], \end{cases}$$

where $\alpha \in (0, 1)$, D^α is the Riemann-Liouville fractional derivative, and ϕ and f are continuous. By using the sub- and super-solution method, they gave some sufficient conditions for the existence of positive solutions.

In this paper, motivated by the work in [9], we are interested in studying the existence and uniqueness of a positive solution for the fractional differential system with variable delays

$${}^c D^\alpha x_i(t) = f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))), \quad i \in \llbracket 1, n \rrbracket, \quad t \geq 0, \quad (1.1)$$

$$x(t) = \Phi(t) \geq 0, \quad t \in [-\tau, 0], \quad (1.2)$$

where ${}^c D^\alpha$ is the Caputo fractional derivative of order $\alpha \in (0, 1)$, $x(t) = (x_1(t), \dots, x_n(t))'$, where $'$ denote the transpose of the vector and $f_i : \mathbb{R}^+ \times C^{n+1} \rightarrow \mathbb{R}$ are continuous such that $C = C([-\tau, \infty], \mathbb{R}^+)$ is the space of continuous function from $[-\tau, \infty]$ to \mathbb{R}^+ . $\Phi(t) = (\phi_1(t), \dots, \phi_n(t))'$ are given vector, such that $\phi_i(t) \in C([-\tau, 0], \mathbb{R}^+)$. τ_i are continuous real-valued functions defined on \mathbb{R}^+ such that $\tau = \max\{\sup_{t \in \mathbb{R}^+} \tau_i(t), i \in \llbracket 1, n \rrbracket\} > 0$.

First, by using the sub- and super-solution method (on a cone), we establish the existence of a global positive solution to the problem (1.1)-(1.2). Second, we show the uniqueness of a positive solution of the problem(1.1)-(1.2) by using the Banach fixed point theorem.

The remainder of this paper is structured as follows. In Section 2, we list some preliminaries to make the paper self-contained. In Section 3, we present and prove our main results on the global existence of a positive solution. Furthermore, the uniqueness of the solution is shown in Section 4. Finally, we provide two examples to illustrate our results.

2. Preliminaries

Let E be a real Banach space. A cone K introduces a partial order \leq in E in the following manner [7]

$$x \leq y \quad \text{if } y - x \in K.$$

Definition 2.1. [7] For $x, y \in E$, the order interval $\langle x, y \rangle$ is defined as

$$\langle x, y \rangle = \{z \in E : x \leq z \leq y\}.$$

Definition 2.2. [7] The functional $h(t, x, x_1, \dots, x_n)$ is nondecreasing with respect to arguments (starting from the second argument) on $I \times E^{n+1}$, if for any $(t, \phi, \phi_1, \dots, \phi_n) \in I \times E^{n+1}$ and $(t, \psi, \psi_1, \dots, \psi_n) \in I \times E^{n+1}$, such that

$$\phi(\theta) \leq \psi(\theta) \text{ and } \phi_i(\theta) \leq \psi_i(\theta), \quad i = 1, 2, \dots, n, \quad \theta \in [-\tau, 0],$$

$h(t, \phi, \phi_1, \dots, \phi_n) \leq h(t, \psi, \psi_1, \dots, \psi_n)$ holds.

Theorem 2.3. [7] Let D be a subset of the cone K of partially ordered space E , $F : D \rightarrow E$ be nondecreasing. If there exist $x_0, y_0 \in D$ such that $x_0 \leq y_0$, $\langle x_0, y_0 \rangle \subset D$ and x_0, y_0 are respectively lower and upper solutions of equation $x - F(x) = 0$, then the equation $x - F(x) = 0$ has minimum solution and maximum solution x^*, y^* in $\langle x_0, y_0 \rangle$ such that $x^* \leq y^*$, when one of the following conditions holds

- (1) K is normal and F is completely continuous;
- (2) K is regular and F is continuous;
- (3) E is reflexive, K is normal, and F is continuous or weak continuous.

In this paper, the functions we are going to manipulate are defined on infinite (unbounded) intervals. Therefore, in our case, the theorem of Arzela-Ascoli does not work. So, we need the following modification [10].

Proposition 2.4. Let $\Omega \subset E$. If the functions $x \in \Omega$ are almost equicontinuous on I and uniformly bounded in the sense of the norm

$$\|x\|_q = \sup_I \{|x(t)|q(t)\},$$

where function q is positive and continuous on I and

$$\lim_{t \rightarrow \infty} \frac{p(t)}{q(t)} = 0,$$

then Ω is relatively compact in E , where $p : I := [0, \infty) \rightarrow (0, \infty)$ be a continuous function such that

$$\sup_I \{|x(t)|p(t)\} < \infty.$$

Recall that the functions $x \in \Omega$ are said to be almost equicontinuous on I if they are equicontinuous in each interval $[0, T]$, $0 < T < \infty$.

Definition 2.5. [3] For all $T > 0$, the Riemann–Liouville fractional integral of order $\alpha \in \mathbb{R}$ of a function $f \in L^1[0, T]$ is given by:

$$I^\alpha f(t) := \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s) ds, \quad t \in [0, T].$$

For $\alpha = 0$, we set $I^0 := Id$, the identity operator.

Definition 2.6. [3] The Caputo fractional derivative of order $\alpha \in \mathbb{R}$ of the function f with $D^n f \in L^1[0, T]$ is defined by

$${}^c D^\alpha f(t) = I^{n-\alpha} D^n f(t) = \frac{1}{\Gamma(n-\alpha)} \int_0^t (t-s)^{n-\alpha-1} f^{(n)}(s) ds, \quad t \geq 0,$$

where $n = [\alpha] + 1$, $[\alpha]$ denotes the integer part of number α and $D = \frac{d}{dt}$.

Obviously, Caputo's derivative of a constant is equal to zero. From the definition of Caputo's derivative, we can acquire the following properties; see [3] and the references therein.

Lemma 2.7. *Let $\alpha > 0$ ($n-1 < \alpha \leq n$), $n = [\alpha] + 1$ and $f \in L^1[0, \infty)$. Then*

$${}^c D^\alpha f(t) = I^{n-\alpha} D^n f(t). \quad (2.1)$$

Lemma 2.8. *Let $\alpha > 0$. Then*

$${}^c D^\alpha I^\alpha f(t) = f(t). \quad (2.2)$$

3. Existence of positive solutions

In this section, we prove the existence of global positive solutions.

Lemma 3.1. *The vector function $x(t) := (x_1(t), \dots, x_n(t))$ is a solution of the problem (1.1) – (1.2) if and only if*

$$x_i(t) = \begin{cases} \phi_i(0) + I^\alpha f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))), & t > 0, \\ \phi_i(0), & t \in [-\tau, 0], \quad i \in \llbracket 1, n \rrbracket. \end{cases}$$

Proof. For $t > 0$, equation (1.1) can be written as

$$I^{1-\alpha} D x_i(t) = f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))).$$

Applying the operator I^α on both sides, we have

$$\begin{aligned} I D x_i(t) &= I^\alpha f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))), \\ x_i(t) - x_i(0) &= I^\alpha f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))). \end{aligned}$$

Then

$$x_i(t) = \phi_i(0) + I^\alpha f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))). \quad (3.1)$$

Conversely, by operating ${}^c D^\alpha$ on both sides of (3.1), we get

$${}^c D^\alpha x_i(t) = {}^c D^\alpha \phi_i(0) + {}^c D^\alpha I^\alpha f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))).$$

Using (2.2) and the fact that Caputo's derivative of a constant is equal to zero, we have

$${}^c D^\alpha x_i(t) = f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))).$$

This completes the proof.

Next, we consider space $E = [C([- \tau, \infty), \mathbb{R}^+)]^n$, where $[C([- \tau, \infty), \mathbb{R}^+)]^n$ is the class of all continuous column n -vectors function with the norm

$$\|x\|_N = \sum_{i=1}^n \sup_{t \in \mathbb{R}^+} \{e^{-Nt} |x_i(t)|\}, \quad x \in E,$$

where $N \in \mathbb{R}^+$ will be chosen later.

Next, we define the cone $K = \{x \in E : x_i(t) \geq 0, t \geq -\tau, i \in \llbracket 1, n \rrbracket\}$, and the subset $D = \{x \in K : x(t) = \Phi(t), -\tau \leq t \leq 0\} \subset K$. We define the integral operator F by

$$F x_i = \begin{cases} \phi_i(t), & t \in [-\tau, 0], \\ \phi_i(0) + I^\alpha f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))), & t > 0, \end{cases} \quad i \in \llbracket 1, n \rrbracket. \quad (3.2)$$

Assume that:

(H₁): there exists $g_i, \psi_{ij} : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ continuous such that

$$|f_i(t, u_i, v_1, \dots, v_n)| \leq g_i(u_i) + \sum_{j=1}^n \psi_{ij}(v_j) \quad \text{for } i \in \llbracket 1, n \rrbracket.$$

(H₂): $\forall A, \exists B_i, B'_i : g_i(A) \subset B_i$ and $\psi_{ij}(A) \subset B'_i$, where A, B_i and B'_i are bounded subset in D for $i \in \llbracket 1, n \rrbracket$.

Lemma 3.2. *Assume that $(H_1) - (H_2)$ holds. Then operator $F : D \rightarrow D$ is completely continuous.*

Proof. From the assumption of continuity of f , we see that $F : D \rightarrow D$ is continuous. Let $G \subset D$ be bounded, i.e. there exists a positive constant l such that $\|x\| \leq l, \forall x \in G$. So, for each $x \in G$, we have for $i \in \llbracket 1, n \rrbracket$:

$$\begin{aligned} |Fx_i(t)| &\leq |\phi_i(0)| + \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} |f_i(s, x_i(s), x_1(s - \tau_1(s)), \dots, x_n(s - \tau_n(s)))| ds \\ &\leq |\phi_i(0)| + \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} g_i(x_i(s)) ds + \sum_{j=1}^n \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} \psi_{ij}(x_j(s - \tau_j(s))) ds. \end{aligned}$$

It follows that

$$\begin{aligned} e^{-Nt} |Fx_i(t)| &\leq e^{-Nt} |\phi_i(0)| + \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{-N(t-s)} e^{-Ns} g_i(x_i(s)) ds + \\ &+ \sum_{j=1}^n \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{-N(t-s+\tau_j(s))} e^{-N(s-\tau_j(s))} \psi_{ij}(x_j(s - \tau_j(s))) ds \\ &\leq \|\phi\|_N + \sup_{\xi \in \mathbb{R}^+} \{e^{-N\xi} g_i(x_i(\xi))\} \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{-N(t-s)} ds + \\ &+ \sum_{j=1}^n \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{-N(t-s+\tau_j(s))} e^{-Nr_j(s)} \psi_{ij}(x_j(r_j(s))) ds / r_j(s) = s - \tau_j(s) \\ &\leq \|\phi\|_N + \sup_{\xi \in \mathbb{R}^+} \{e^{-N\xi} g_i(x_i(\xi))\} \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{-N(t-s)} ds + \\ &+ \sum_{j=1}^n \sup_{\xi \in \mathbb{R}^+} \{e^{-N\xi} \psi_{ij}(x_j(\xi))\} \int_0^{Nt} \frac{u^{\alpha-1}}{N^\alpha \Gamma(\alpha)} e^{-u} e^{-N\tau_j(t-\frac{u}{N})} du \\ &\leq \|\phi\|_N + \sup_{\xi \in \mathbb{R}^+} \{e^{-N\xi} g_i(x_i(\xi))\} \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{-N(t-s)} ds + \\ &+ \sum_{j=1}^n \sup_{\xi \in \mathbb{R}^+} \{e^{-N\xi} \psi_{ij}(x_j(\xi))\} \int_0^{Nt} \frac{u^{\alpha-1}}{N^\alpha \Gamma(\alpha)} e^{-u} du. \end{aligned}$$

From hypothesis (H_2) , there exists L_i, L'_j such that $L_i = \sup_{t \in \mathbb{R}^+} \{e^{-Nt} |g_i(x_i(t))|\}$, $L'_j = \sup_{t \in \mathbb{R}^+} \{e^{-Nt} |\psi_{ij}(x_j(t))|\}$, $\forall j$. Then

$$\begin{aligned} e^{-Nt} |Fx_i(t)| &\leq \|\phi\|_N + L_i \int_0^{Nt} \frac{u^{\alpha-1}}{N^\alpha \Gamma(\alpha)} e^{-u} du + \sum_{j=1}^n L'_j \int_0^{Nt} \frac{u^{\alpha-1}}{N^\alpha \Gamma(\alpha)} e^{-u} du \\ &\leq l + \frac{L_i + \sum_{j=1}^n L'_j}{N^\alpha}. \end{aligned}$$

Hence FG is bounded.

Next, we show that FG is locally (almost) equicontinuous. There are three possible cases for $i \in \llbracket 1, n \rrbracket$:

Case 1. For each $x \in G$, $\varepsilon_i > 0, \forall T \in]0, \infty)$, $t_1, t_2 \in [0, T]$, $t_1 < t_2$. Let $\delta_i = \left(\frac{\varepsilon_i \Gamma(\alpha+1)}{2(c_i + \sum_{j=1}^n c'_j)} \right)^{\frac{1}{\alpha}}$, when $t_2 - t_1 < \delta_i$, we have:

$$\begin{aligned}
& |Fx_i(t_1) - Fx_i(t_2)| \\
& \leq \frac{1}{\Gamma(\alpha)} \int_0^{t_1} \left((t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1} \right) \left| g_i(x_i(s)) + \sum_{j=1}^n \psi_{ij}(x_j(s - \tau_j(s))) \right| ds + \\
& + \int_{t_1}^{t_2} \frac{(t_2 - s)^{\alpha-1}}{\Gamma(\alpha)} \left| g_i(x_i(s)) + \sum_{j=1}^n \psi_{ij}(x_j(s - \tau_j(s))) \right| ds \\
& \leq \frac{1}{\Gamma(\alpha)} \int_0^{t_1} \left((t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1} \right) \left\{ g_i(x_i(s)) + \sum_{j=1}^n \psi_{ij}(x_j(s - \tau_j(s))) \right\} ds + \\
& + \int_{t_1}^{t_2} \frac{(t_2 - s)^{\alpha-1}}{\Gamma(\alpha)} \left\{ g_i(x_i(s)) + \sum_{j=1}^n \psi_{ij}(x_j(s - \tau_j(s))) \right\} ds,
\end{aligned}$$

$\exists l > 0$ such that for $x \in G$, $\|x\| \leq l$ then $|x_i(t)| \leq le^{Nt} \leq le^{NT}$. Indeed, the subset $X = \{x(t), t \in [0, T], x \in G\}$ is a closed bounded subset. Then g_i, ψ_{ij} have a maximum on X . Therefore, $\exists c_i, c'_j : c_i = \sup_{t \in [0, T]} g_i(x_i(t))$, $c'_j = \sup_{t \in [0, T]} \psi_{ij}(x_i(t - \tau_i))$, $\forall i, j = 1, 2, \dots, n$. Then

$$\begin{aligned}
& |Fx_i(t_1) - Fx_i(t_2)| \\
& \leq \frac{1}{\Gamma(\alpha)} \int_0^{t_1} \left((t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1} \right) (c_i + \sum_{j=1}^n c'_j) ds + \\
& + \int_{t_1}^{t_2} \frac{(t_2 - s)^{\alpha-1}}{\Gamma(\alpha)} (c_i + \sum_{j=1}^n c'_j) ds \\
& \leq \frac{c_i + \sum_{j=1}^n c'_j}{\Gamma(\alpha)} \left\{ \int_0^{t_1} \left((t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1} \right) ds + \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} ds \right\} \\
& \leq \frac{c_i + \sum_{j=1}^n c'_j}{\alpha \Gamma(\alpha)} \left\{ (t_2 - t_1)^\alpha + t_1^\alpha - t_2^\alpha + (t_2 - t_1)^\alpha \right\} \\
& < 2 \frac{c_i + \sum_{j=1}^n c'_j}{\Gamma(\alpha+1)} (t_2 - t_1)^\alpha < 2 \frac{c_i + \sum_{j=1}^n c'_j}{\Gamma(\alpha+1)} \delta_i^\alpha = \varepsilon_i.
\end{aligned}$$

Case 2. For each $x \in G$, $\varepsilon_i > 0$, $t_1 \in [-\tau, 0]$, $t_2 \in [0, T]$, $\forall T \in [0, \infty)$. Since $\phi_i \in C[-\tau, 0]$, we see that $\exists \delta' : |\phi_i(t_1) - \phi_i(0)| < \frac{\varepsilon_i}{2}$ when $0 - t_1 < \delta'$. If $t_2 - t_1 < \delta_i$, $\delta_i = \min \left(\delta', \left(\frac{\varepsilon_i \Gamma(\alpha+1)}{2(c_i + \sum_{j=1}^n c'_j)} \right)^{\frac{1}{\alpha}} \right)$, we have

$$\begin{aligned}
& |Fx_i(t_1) - Fx_i(t_2)| \\
& \leq |\phi_i(t_1) - \phi_i(0)| + \int_0^{t_2} \frac{(t_2-s)^{\alpha-1}}{\Gamma(\alpha)} |f_i(s, x_i(s), x_1(s - \tau_1(s)), \dots, x_n(s - \tau_n(s)))| ds \\
& \leq \frac{\varepsilon_i}{2} + \int_0^{t_2} \frac{(t_2-s)^{\alpha-1}}{\Gamma(\alpha)} \left\{ g_i(x_i(s)) + \sum_{j=1}^n \psi_{ij}(x_j(s - \tau_j(s))) \right\} ds \\
& < \frac{\varepsilon_i}{2} + \frac{c_i + \sum_{j=1}^n c'_j}{\Gamma(\alpha+1)} \delta_i^\alpha \\
& < \frac{\varepsilon_i}{2} + \frac{\varepsilon_i}{2} = \varepsilon_i.
\end{aligned}$$

Case 3. For each $x \in G$, $\varepsilon_i > 0$, $t_1, t_2 \in [-\tau, 0]$, by continuity of ϕ_i , when $t_2 - t_1 < \delta_i$, we have

$$|Fx_i(t_1) - Fx_i(t_2)| = |\phi_i(t_1) - \phi_i(t_2)| < \varepsilon_i.$$

Therefore, FG is equicontinuous in each bounded interval. We now appeal proposition (2.4) to conclude that FG is relatively compact. Hence operator F is completely continuous. This completes the proof.

Definition 3.3. The function $u \in E$ is called a lower solution of problem (1.1)-(1.2) if

$${}^c D^\alpha u_i(t) \leq f_i(t, u_i(t), u_1(t - \tau_1(t)), \dots, u_n(t - \tau_n(t))), \quad t \geq 0, \quad i \in \llbracket 1, n \rrbracket,$$

and

$$u(t) \leq \Phi(t), \quad t \in [-\tau, 0].$$

Similarly, function $v \in E$ is called an upper solution of problem (1.1)-(1.2) if

$${}^c D^\alpha v_i(t) \geq f_i(t, v_i(t), v_1(t - \tau_1(t)), \dots, v_n(t - \tau_n(t))), \quad t \geq 0, \quad i \in \llbracket 1, n \rrbracket,$$

and

$$v(t) \geq \Phi(t), \quad t \in [-\tau, 0].$$

If the strict inequalities hold, then $u(t), v(t)$ are called strict lower and upper solutions.

Theorem 3.4. Assume that $(H_1) - (H_2)$ hold, and $(H_3 :)$ for $i \in \llbracket 1, n \rrbracket : f_i : \mathbb{R}^+ \times E^{n+1} \rightarrow \mathbb{R}$ is continuous and nondecreasing function for each $t \in [0, \infty)$. (H_4) $u_0 = (u_0^1, \dots, u_0^n)'$, $v_0 = (v_0^1, \dots, v_0^n)'$ are respectively lower and upper solutions of (1.1)-(1.2) satisfying $u_0(t) \leq v_0(t)$, $t \in [0, \infty)$, $u_0, v_0 \in D$. Then (1.1)-(1.2) has at least a global positive solution.

Proof. By Lemma (3.2), we have $F : D \rightarrow D$ is completely continuous. And by (3.2), u_0^i, v_0^i are lower and upper solutions of F respectively. By (H_3) , $x, y \in D$, $x \leq y$, we have for $i \in \llbracket 1, n \rrbracket$:

$$\begin{aligned} Fx_i(t) &= x_i(0) + I^\alpha f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))) \\ &\leq y_j(0) + I^\alpha f_i(t, y_i(t), y_1(t - \tau_1(t)), \dots, y_n(t - \tau_n(t))) \\ &\leq Fy_i(t). \end{aligned}$$

Hence F is a nondecreasing operator. Clearly, for $i \in \llbracket 1, n \rrbracket : Fu_0^i \geq u_0^i, Fv_0^i \leq v_0^i$ by definition of lower and upper solution of F . Hence, $F : \langle u_0, v_0 \rangle \rightarrow \langle u_0, v_0 \rangle$ is a compact continuous operator. As K is a normal cone, by Theorem 2.3, F has a fixed point $x \in \langle u_0, v_0 \rangle$. This completes the proof.

Remark 3.5. The condition (H_4) in Theorem 3.4 can be replaced by (H_5) : there exists a positive function $H(t) = (h_1(t), \dots, h_n(t))'$, $t \geq 0$, such that

$$f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))) \leq h_i(t), \quad t \geq 0,$$

where $\forall t \geq 0 : \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} h_i(s) ds < \infty$. We can easily find lower and upper solutions of the problem as follow. Consider the problem

$$\begin{cases} {}^c D^\alpha u_0^i(t) = 0, & t \geq 0 \\ u_0^i(t) = \phi_i(t), & -\tau \leq t \leq 0 \end{cases}, \quad i = 1, 2, \dots, n. \quad (3.3)$$

Obviously, the equation ${}^c D^\alpha u_0^i(t) = 0$ has a solution $u_0^i(t) = \phi_i(0)$, $t \geq 0$, $i = 1, 2, \dots, n$, which is a lower solution of the problem (1.1) – (1.2). Similarly, consider the problem

$$\begin{cases} {}^c D^\alpha v_0^i(t) = h_i(t) \geq f_i(t, x_i(t), x_1(t - \tau_1(t)), \dots, x_n(t - \tau_n(t))), & t \geq 0 \\ v_0^i(t) = \phi_i(t), & -\tau \leq t \leq 0 \end{cases}, \quad i \in \llbracket 1, n \rrbracket.$$

We have

$$v_0^i(t) = \phi_i(0) + \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} h_i(s) ds, \quad t \geq 0,$$

which is an upper solution of the problem (1.1) – (1.2) and $u_0^i(t) \leq v_0^i(t)$. By Theorem 3.4, (1.1) – (1.2) has at least a positive solution.

4. Uniqueness of solutions

In this section, we discuss the uniqueness of solutions.

Theorem 4.1. *Let $f_i : \mathbb{R}^+ \times [C([- \tau, \infty), \mathbb{R}^+)]^{n+1} \rightarrow \mathbb{R}$ be continuous and satisfy the Lipschitz condition for $i \in \llbracket 1, n \rrbracket$: $|f_i(t, u_i, u_1, \dots, u_n) - f_i(t, v_i, v_1, \dots, v_n)| \leq l_i |u_i - v_i| + \sum_{j=1}^n k_{ij} |u_j - v_j|$, $i \in \llbracket 1, n \rrbracket$. Then (1.1) – (1.2) has a unique global positive solution.*

Proof. Letting $u, v \in D$, we have

$$\begin{aligned} & |Fu_i(t) - Fv_i(t)| \\ & \leq \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left\{ l_i |u_i(s) - v_i(s)| + \sum_{j=1}^n k_{ij} |u_j(s - \tau_j(s)) - v_j(s - \tau_j(s))| \right\} ds \\ & \leq l_i \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} |u_i(s) - v_i(s)| ds + \sum_{j=1}^n k_{ij} \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} |u_j(s - \tau_j(s)) - v_j(s - \tau_j(s))| ds. \end{aligned}$$

Let $l = \sum_{i=1}^n |l_i|$, $k = \sum_{i=1}^n |k_i| = \sum_{j=1}^n \max_{\forall i} |k_{ij}|$. Then

$$\begin{aligned} & e^{-Nt} |Fu_j(t) - Fv_j(t)| \\ & \leq l_i \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{-N(t-s)} e^{-Ns} |u_i(s) - v_i(s)| ds + \\ & + k_i \sum_{j=1}^n \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{-N(t-s+\tau_j)} e^{-N(s-\tau_j)} |u_j(s - \tau_j(s)) - v_j(s - \tau_j(s))| ds. \\ & \leq \|u - v\|_N \frac{l_i}{N^\alpha} \int_0^{Nt} \frac{u^{\alpha-1} e^{-u}}{\Gamma(\alpha)} du + nk_i \|u - v\|_N \int_0^{Nt} \frac{u^{\alpha-1} e^{-u}}{N^\alpha \Gamma(\alpha)} du \\ & \leq \frac{l_i}{N^\alpha} \|u - v\|_N + \frac{k_i}{N^\alpha} \|u - v\|_N. \end{aligned}$$

Hence, we have

$$\begin{aligned} \|Fu - Fv\|_N &= \sum_{i=1}^n \sup_{t \in \mathbb{R}^+} e^{-Nt} |Fu_i(t) - Fv_i(t)| \\ &\leq \sum_{i=1}^n \frac{l_i + nk_i}{N^\alpha} \|u - v\|_N \\ &\leq \frac{l + nk}{N^\alpha} \|u - v\|_N. \end{aligned}$$

It follows that

$$\|Fu - Fv\|_N \leq \frac{l + nk}{N^\alpha} \|u - v\|_N.$$

We choose N large enough such that $\frac{l + nk}{N^\alpha} < 1$. By Banach fixed point theorem, F has a unique fixed point in D , which is the unique positive solution. This completes the proof.

5. Examples

Example 5.1. Consider the problem

$$\begin{cases} {}^c D^\alpha x_i(t) = \sum_{j=1}^n a_{ij} x_j(t - \tau_j(t)), & t \geq 0 \\ x(t) = \Phi(t) \geq 0, & -\tau \leq t \leq 0 \end{cases}, \quad i \in \llbracket 1, n \rrbracket, \quad (5.1)$$

where $A = (a_{ij})_{n \times n}$ is given matrix. The hypothesis (H_1) - (H_4) are verified. By Theorem 3.4, problem (5.1) has at least a global positive solution. In addition, $\sum_{j=1}^n a_{ij} x_j(t - \tau_j(t))$ satisfies the Lipschitz condition. By Theorem 4.1, the problem (5.1) has unique global positive solution.

Example 5.2. Consider the problem

$$\begin{cases} {}^c D^\alpha x_i(t) = \sum_{k=1}^n \frac{x_k^2(t - \tau_k(t))}{1 + x_k^2(t - \tau_k(t))}, & t \geq 0 \\ x(t) = \Phi(t) \geq 0, & -\tau \leq t \leq 0 \end{cases}, \quad i \in \llbracket 1, n \rrbracket. \quad (5.2)$$

The hypothesis $(H_1) - (H_4)$ are verified. Using Theorem 3.4, we find that problem (5.2) has at least a global positive solution.

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